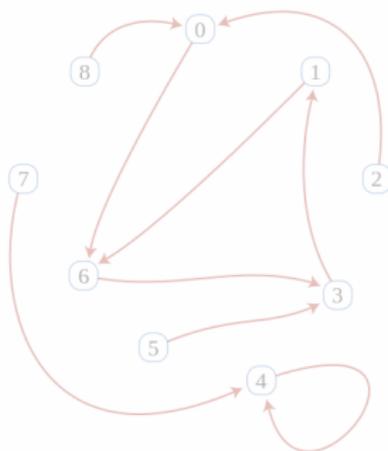




Element Distinctness, Birthday Paradox, and



1-out Pseudorandom Graphs

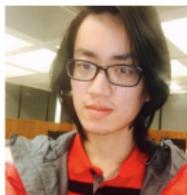


Hongxun Wu

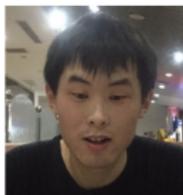
IIS, Tsinghua University

42	3	23	1	12	30	42	15
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Authors of this work



Lijie Chen



Ce Jin



R. Ryan Williams

我

Hongxun Wu

Lijie Chen, Ce Jin, and R. Ryan Williams are from MIT.

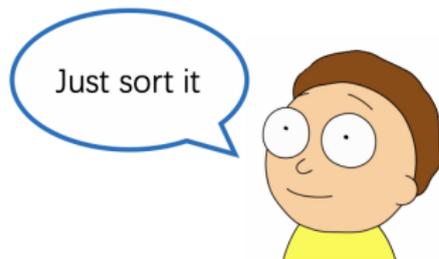
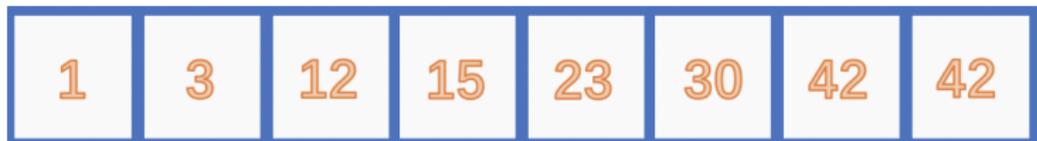
Element Distinctness

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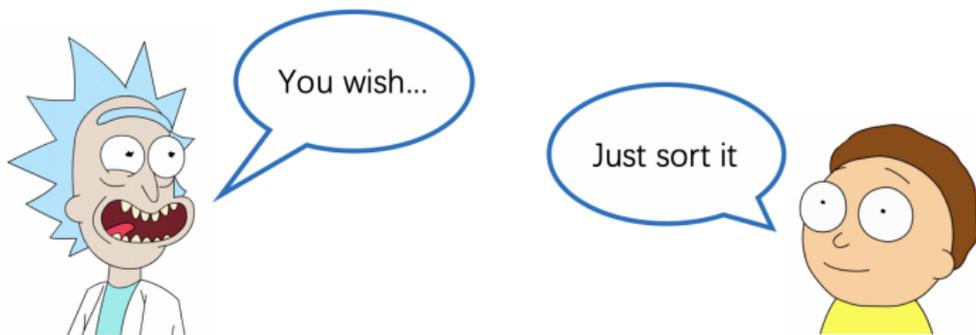
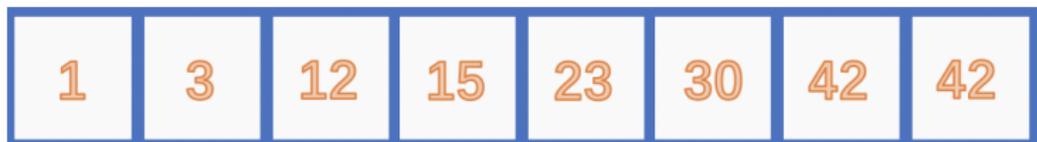


- INPUT: n positive integers a_1, a_2, \dots, a_n with $a_i \leq \text{poly}(n)$.
- Decide whether all a 's are distinct.

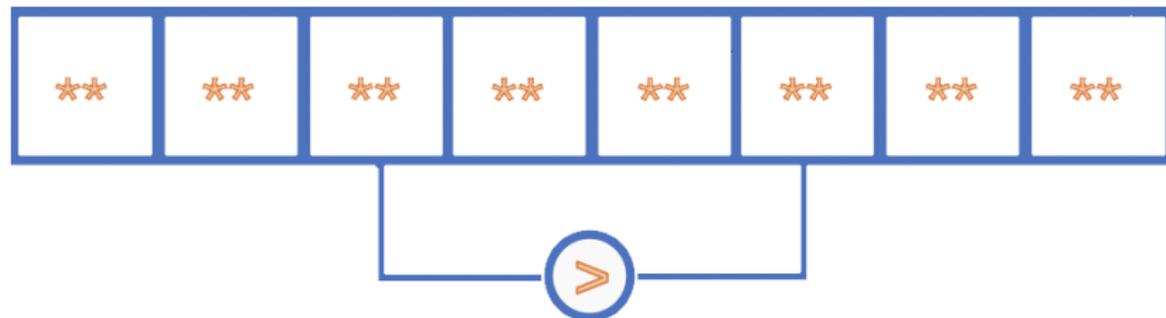
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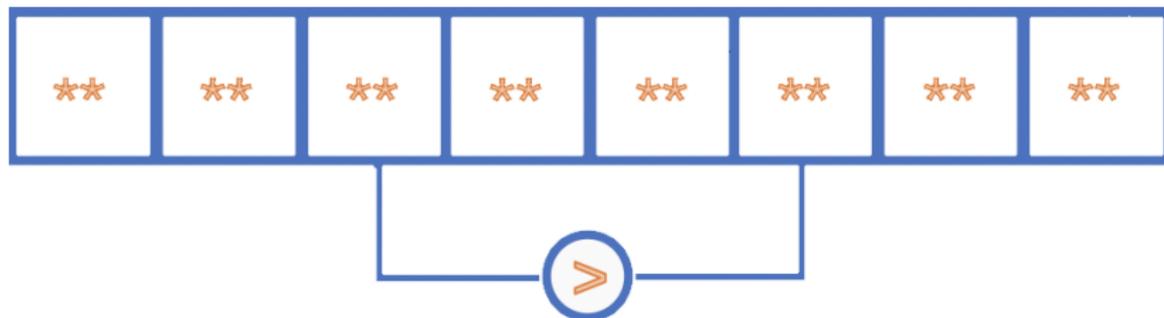


Comparison model



- No direct access to the INPUT a .
- Each query (i, j) returns one of $a_i < a_j$, $a_i = a_j$, $a_i > a_j$.

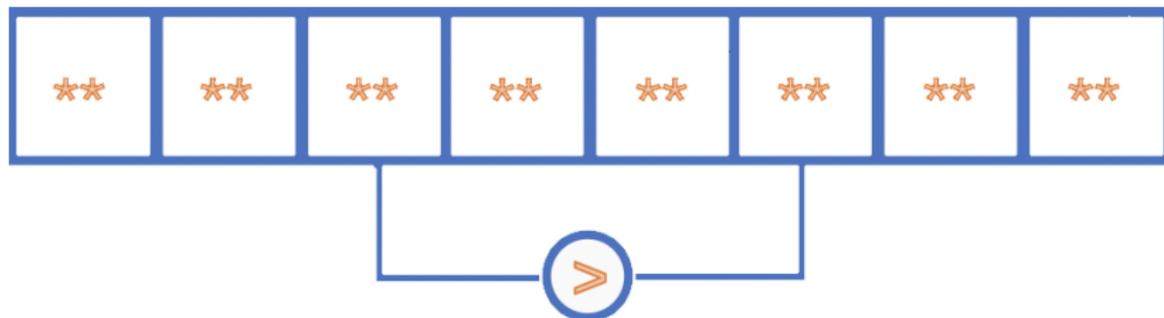
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Time-Space tradeoff [BFMADH⁺87, Yao88]

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Element distinctness requires $TS = \Omega(n^{2-o(1)})$ in Comparison model.

- When $S = O(\text{polylog } n)$, $T = \Omega(n^{2-o(1)})$.



- Random access to read-only input.
- Working memory has a (relatively small) size S .



Time-Space tradeoff [BCM13]

- Assuming the existence of *Random Oracle*, there is an algorithm with $T^2S = \tilde{O}(n^3)$.



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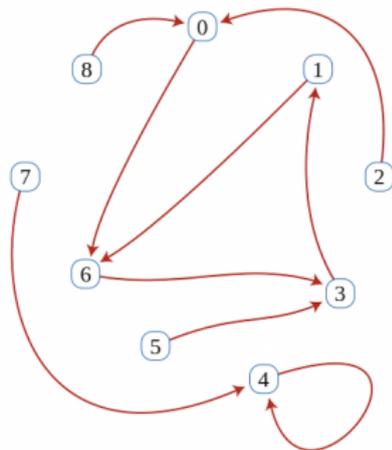
- Assuming the existence of *Random Oracle*, there is an algorithm with $T^2S = \tilde{O}(n^3)$.
- When $S = \tilde{O}(1)$, $T = \tilde{O}(n^{1.5})$.
- In the rest of this talk, we always assume there is only one collision ($a_i = a_j$).

1-out Graph and Birthday Paradox

Pollard's ρ method [BCM13]

Assuming the existence of *Random Oracle*, when $S = \tilde{O}(1)$, there is an algorithm with $T = \tilde{O}(n^{1.5})$.

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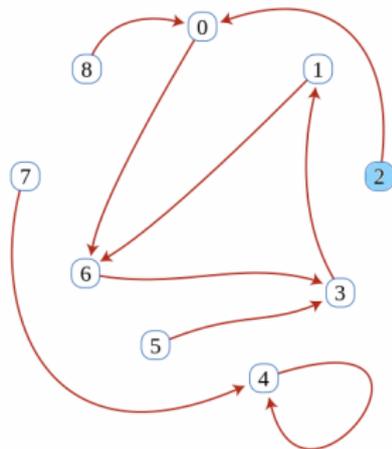


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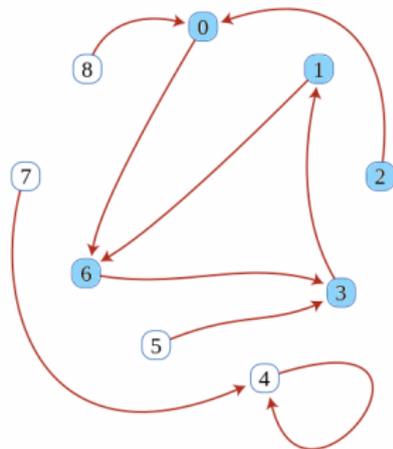


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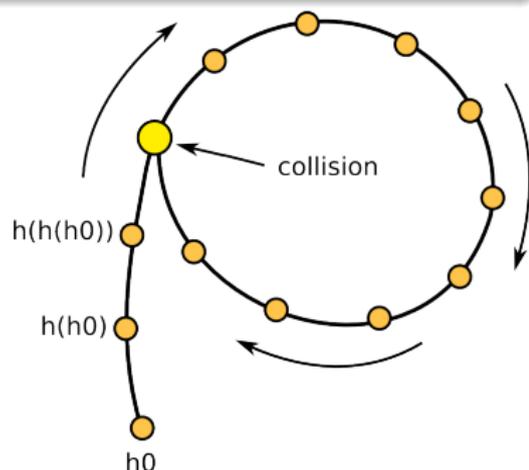


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Suppose $f^*(s)$ is the set of vertices reachable from s .

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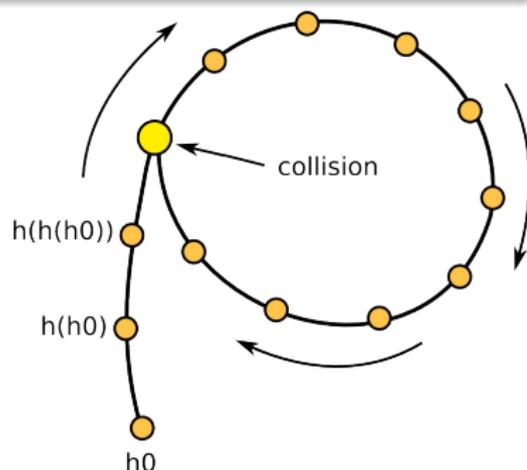


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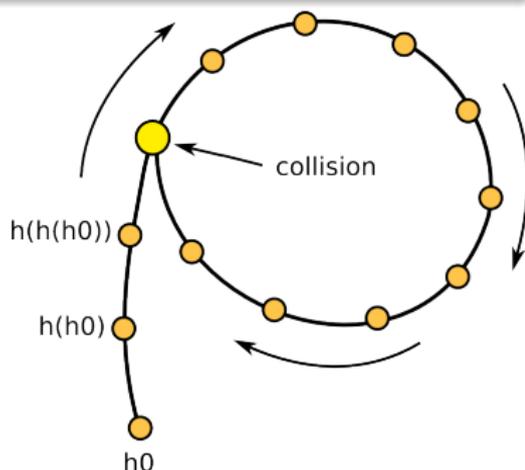


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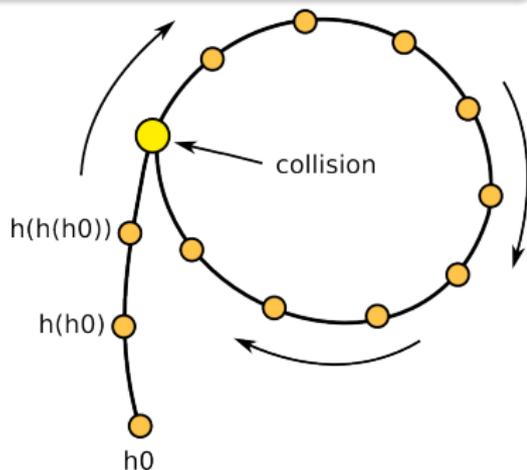
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- So each cycle-finding takes $O(\sqrt{n})$ time and finds any collision u, v with probability $\Omega(1/n)$.
- Repeat $O(n)$ times. It takes $O(n^{1.5})$ time in total.



Our Main Lemma

There exists a family $\{r_{\text{seed}}\}$ of hash functions efficiently samplable with seed length $O(\text{polylog } n)$, and the graph defined by $\{r_{\text{seed}}\}$ (instead of *Random Oracle* R) satisfy

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Our Result

~~Assuming the existence of *Random Oracle*~~, when $S = O(\text{polylog } n)$, there is a RAM algorithm for Element Distinctness with $T = \tilde{O}(n^{1.5})$.

Low-space Algorithm for Subset Sum [BGNV18]

Assuming the existence of *Random Oracle*, Subset Sum and Knapsack can be solved by a Monte Carlo algorithm in $O^*(2^{0.86n})$ time, with $O(\text{poly}(n))$ space.

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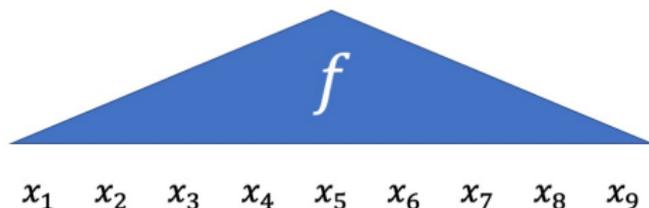
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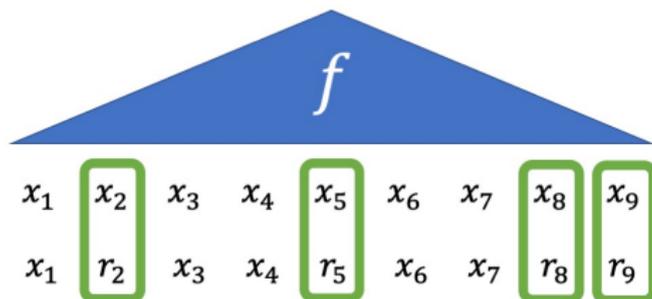


This is Ryan O'Donnell's Youtube lecture which is a masterpiece.



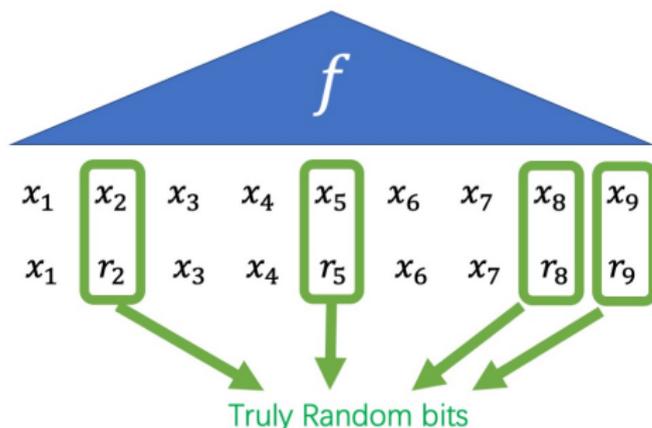
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Toy Example: Two levels

Recall the input $a_1, a_2, \dots, a_n \in [m]$.

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Suppose we have the following:

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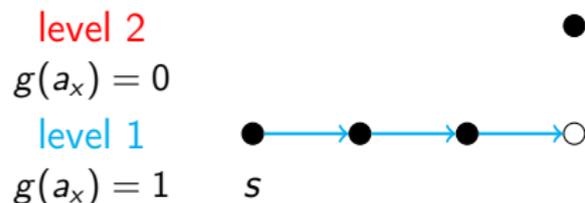


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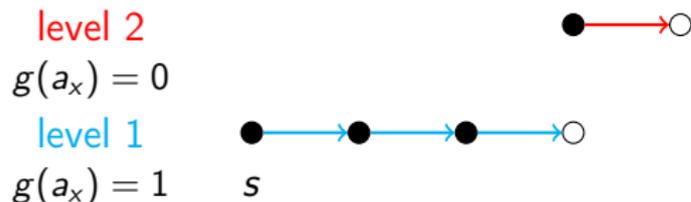


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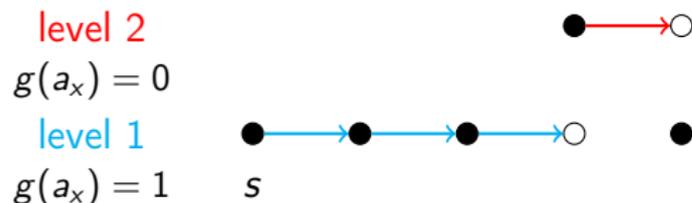


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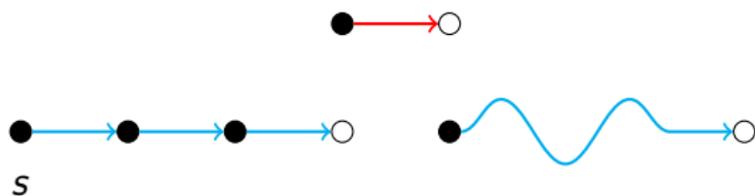
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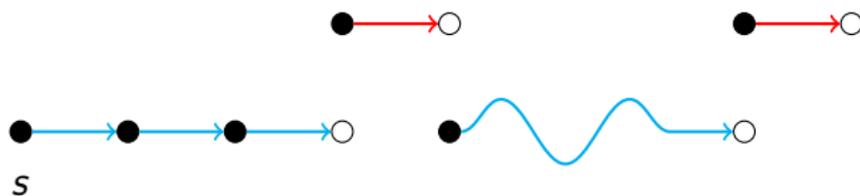
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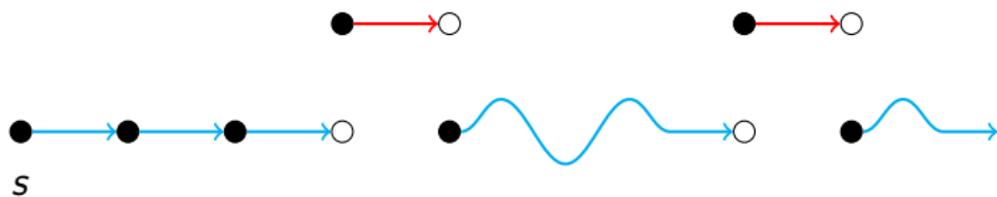
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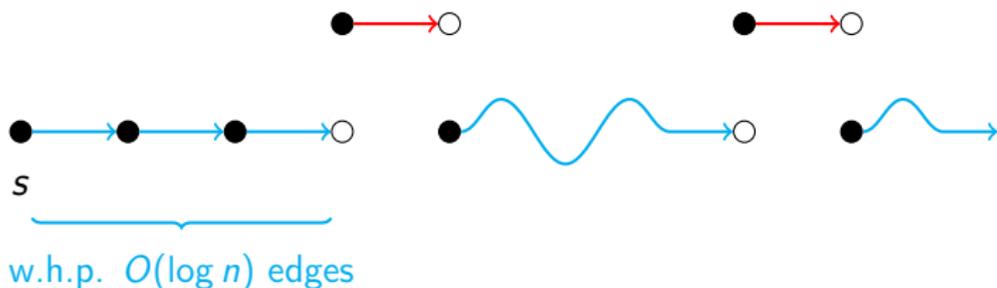
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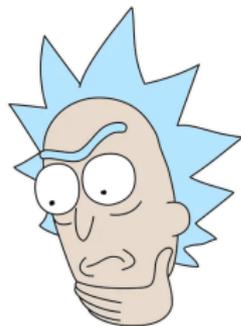
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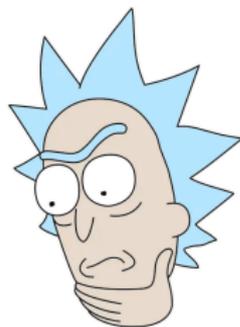


Sanity Check

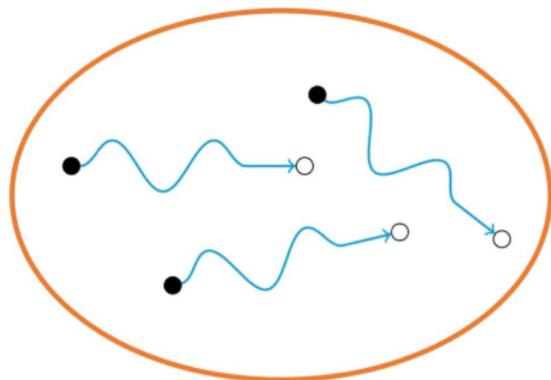


- Why this might be a good idea?

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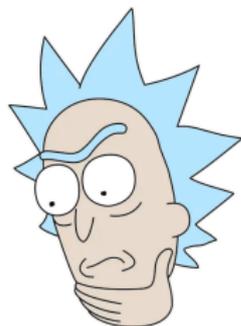


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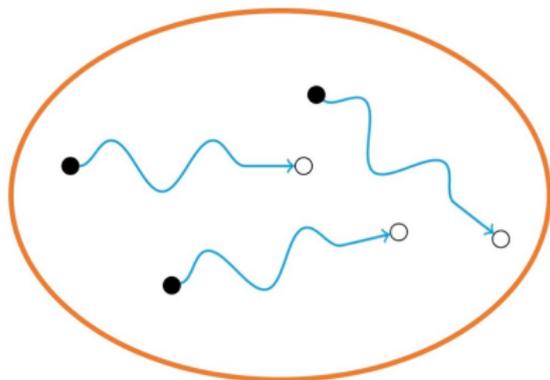


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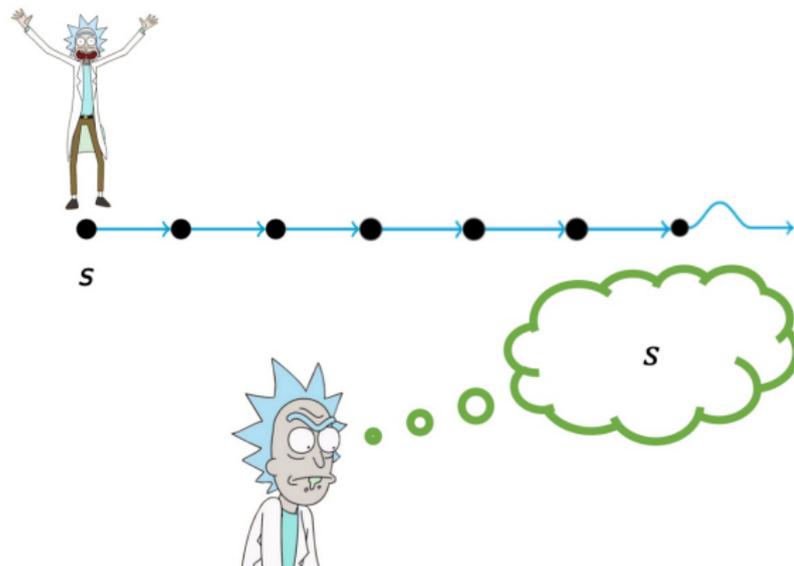
- Each subpath has length $O(\log n)$.
- Every **level 2** edge is an independent sample of a subpath.

Recall our goal.

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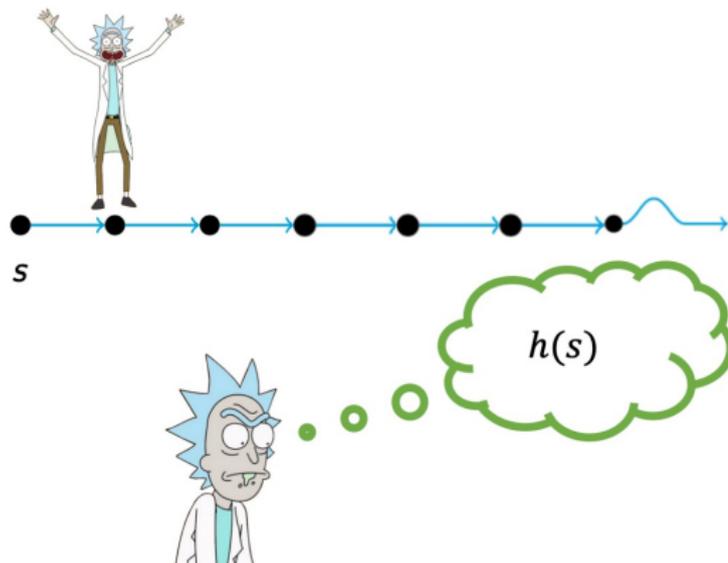
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Intuition: Memory Eraser



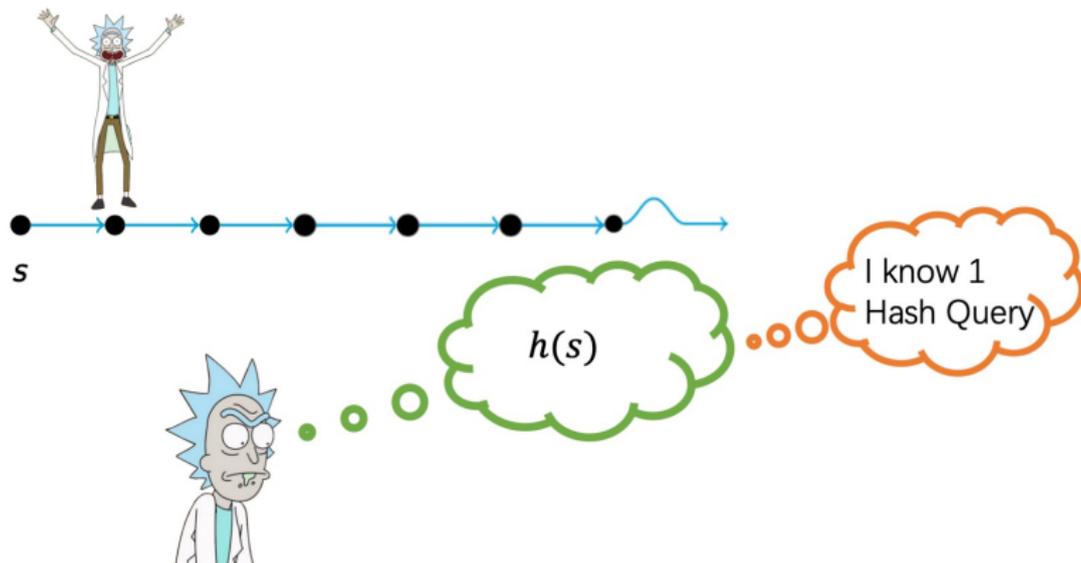
- “Memory” of a random walk: The current vertex it is at.

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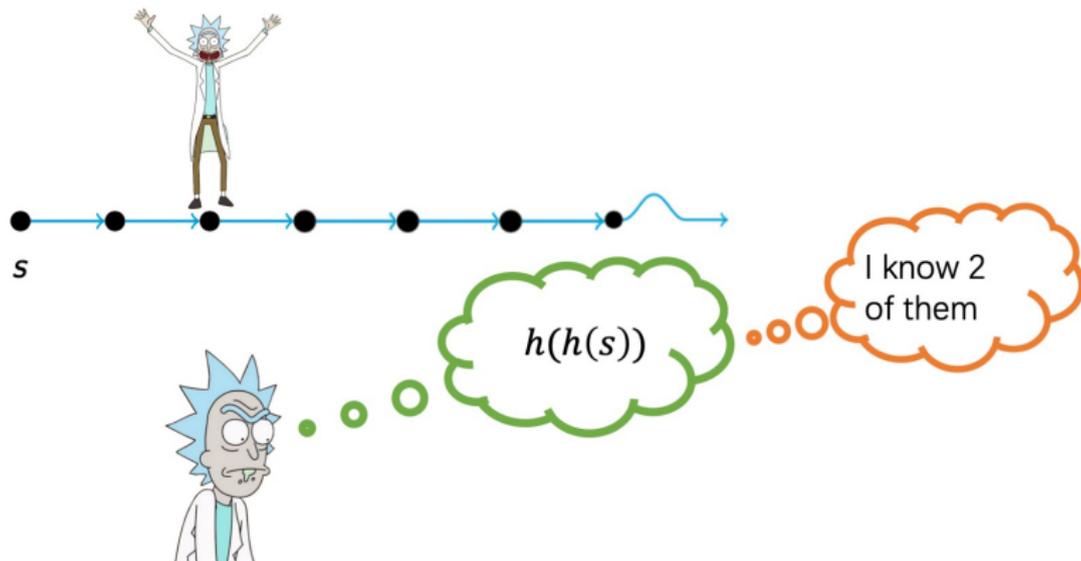
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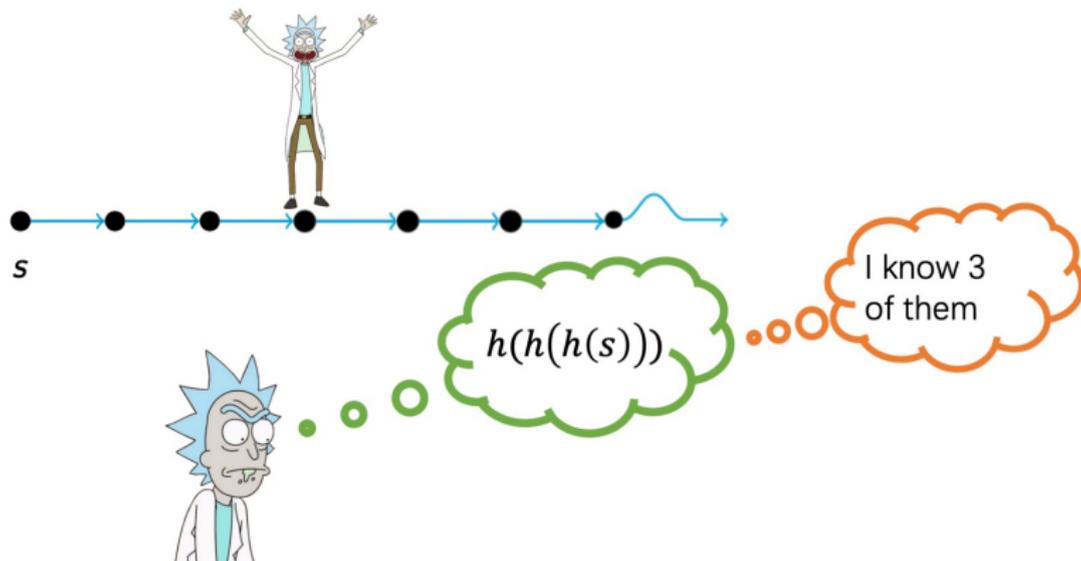
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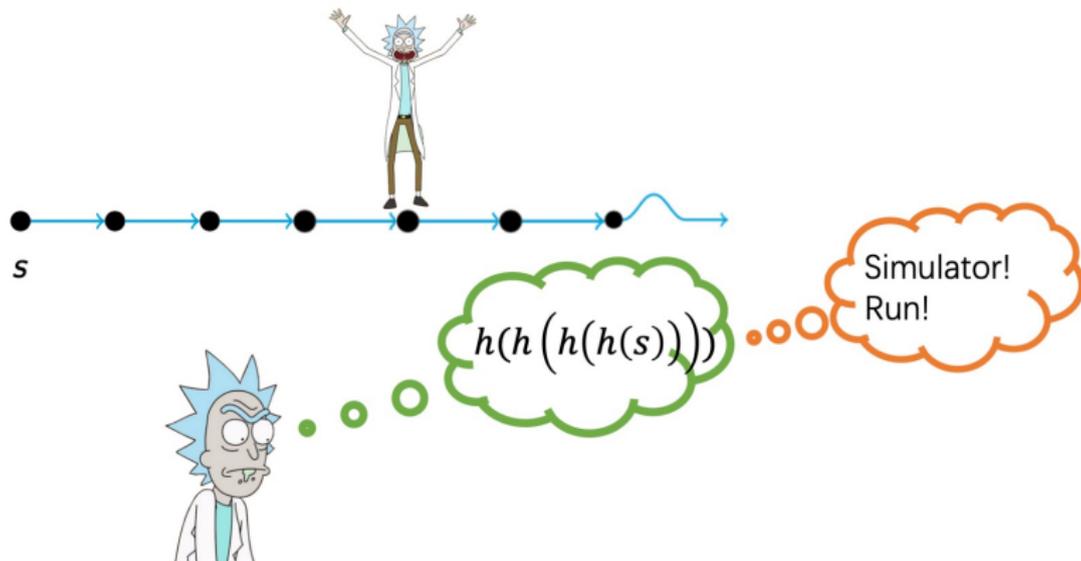
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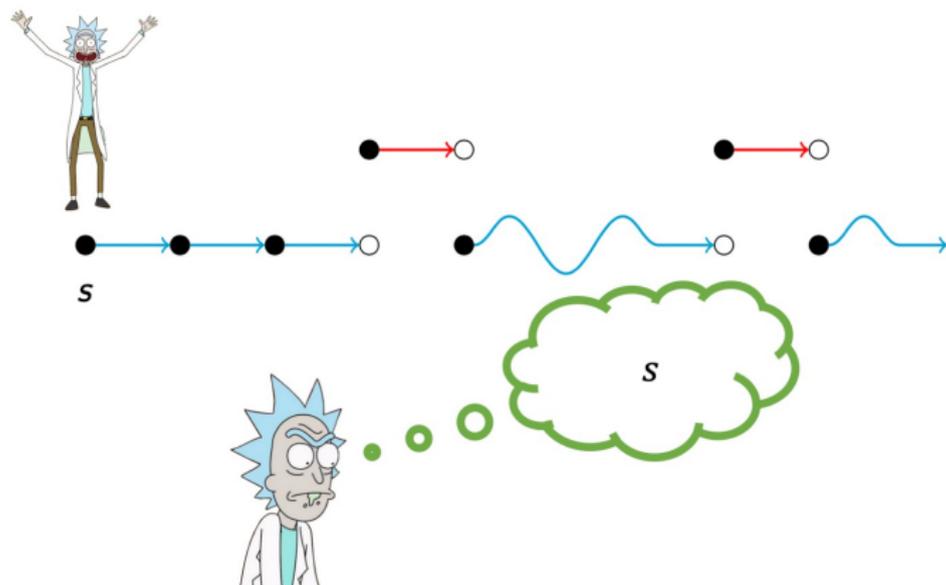
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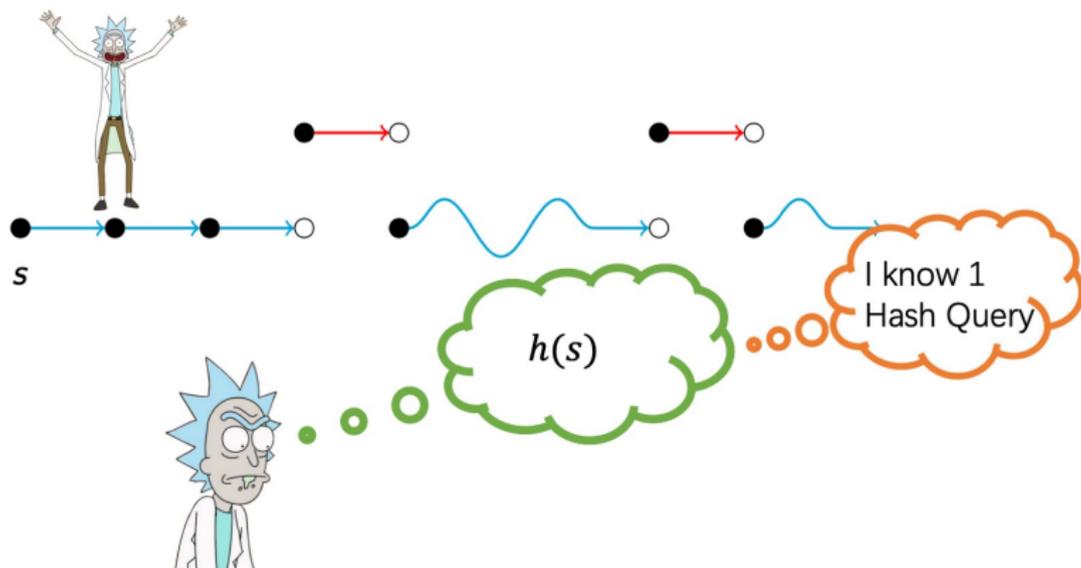
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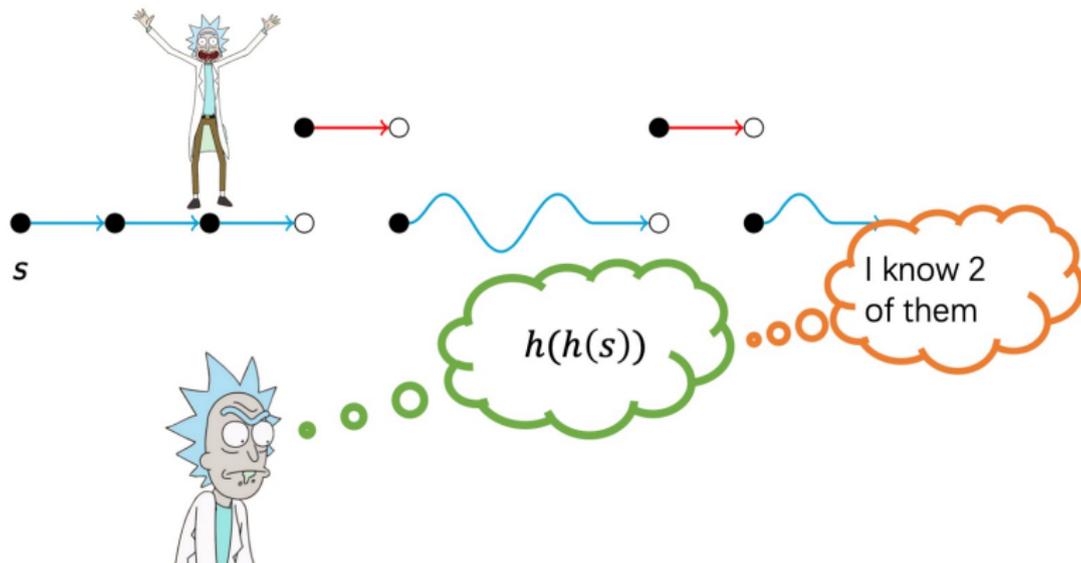
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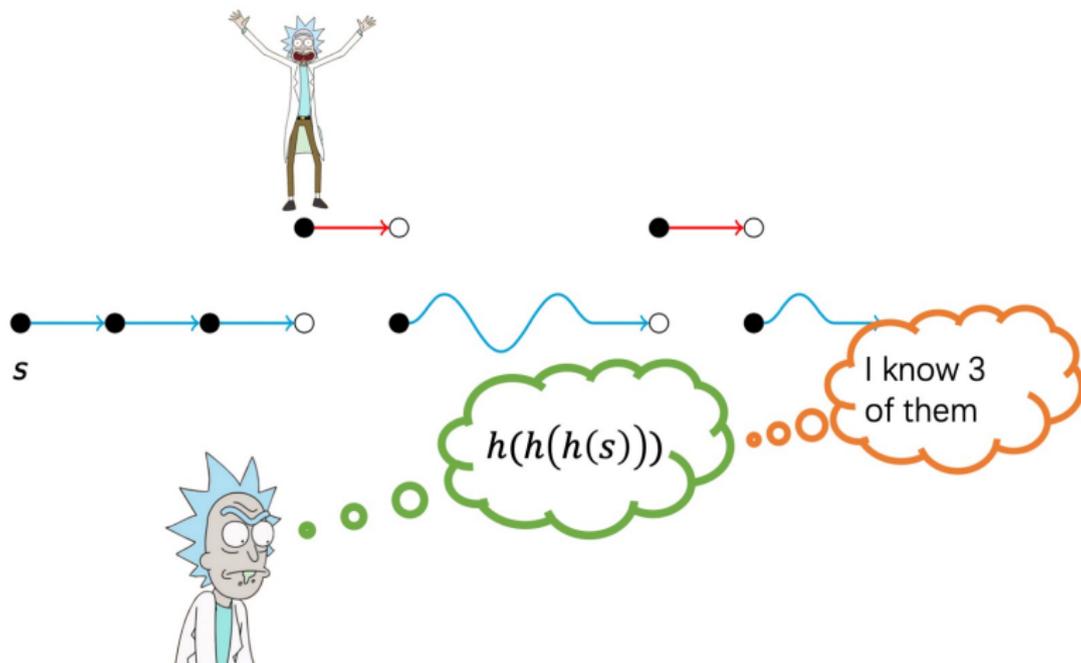
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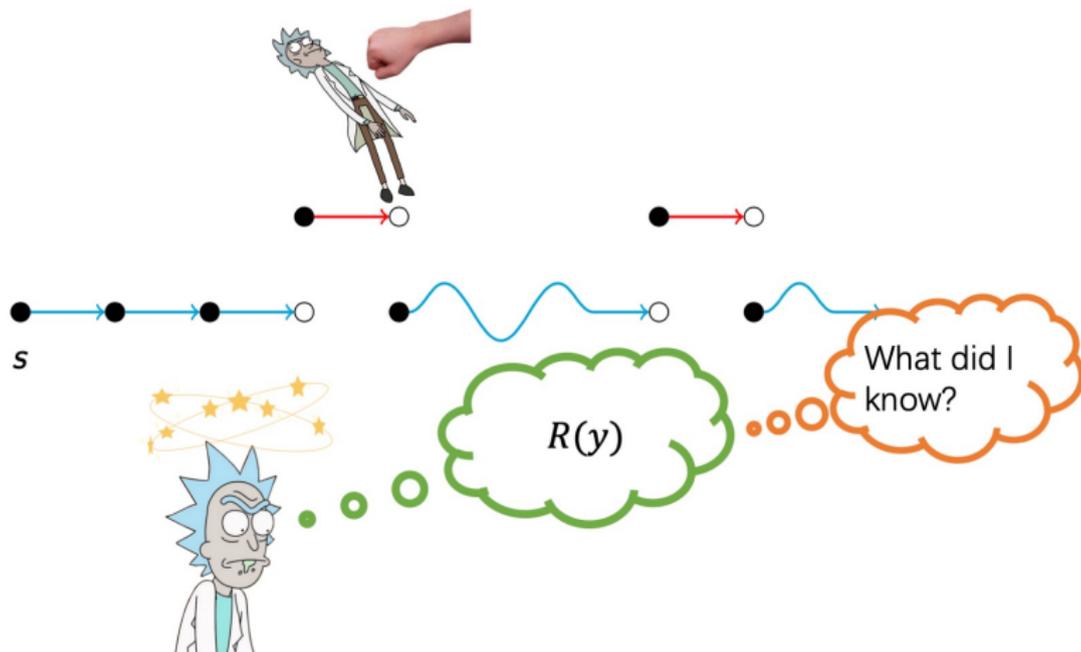
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Our Construction via Iterative Restriction

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Now we sample $O(\log n)$ many hash functions $\{r_i, g_i\}_{i \in [\ell]}$.

Each $r_i : [m] \rightarrow [n]$ and $g_i : [m] \rightarrow [2]$ are $O(\log n)$ -wise independent.

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Each $r_i : [m] \rightarrow [n]$ and $g_i : [m] \rightarrow [2]$ are $O(\log n)$ -wise independent.

Then we set $h_{\ell+1}(a_x) = \perp$ and

$$h_i(a_x) = \begin{cases} h_{i+1}(a_x) & g_i(a_x) = 0 \\ r_i(a_x) & g_i(a_x) = 1 \end{cases}$$

Finally, we set $h = h_1$.

Our Construction via Iterative Restriction

level 5

level 4

level 3

level 2

level 1 ●
 $g_1(a_x) = 1$ s



The Random Walk

Our Construction via Iterative Restriction

level 5

level 4

level 3

level 2

level 1 ● ○
 $g_1(a_x) = 0$ s



The Random Walk

Our Construction via Iterative Restriction

level 5

level 4

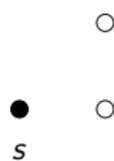
level 3

level 2

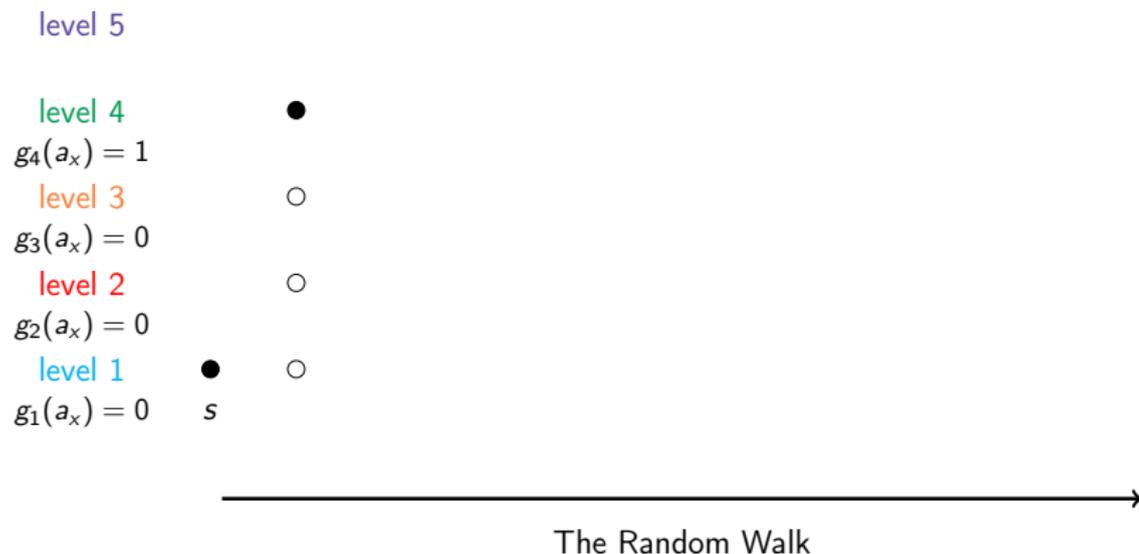
$$g_2(a_x) = 0$$

level 1

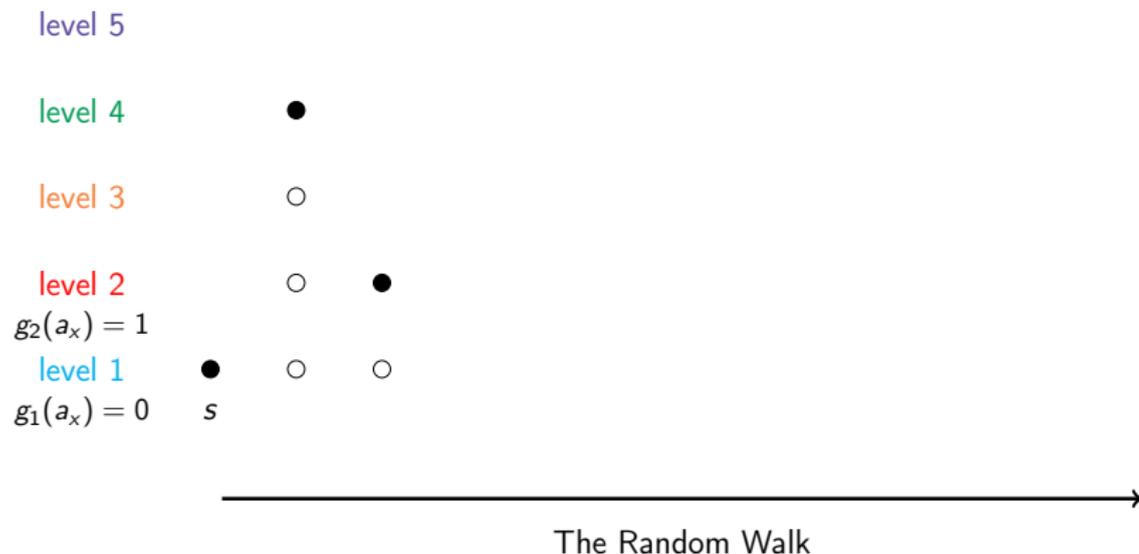
$$g_1(a_x) = 0$$



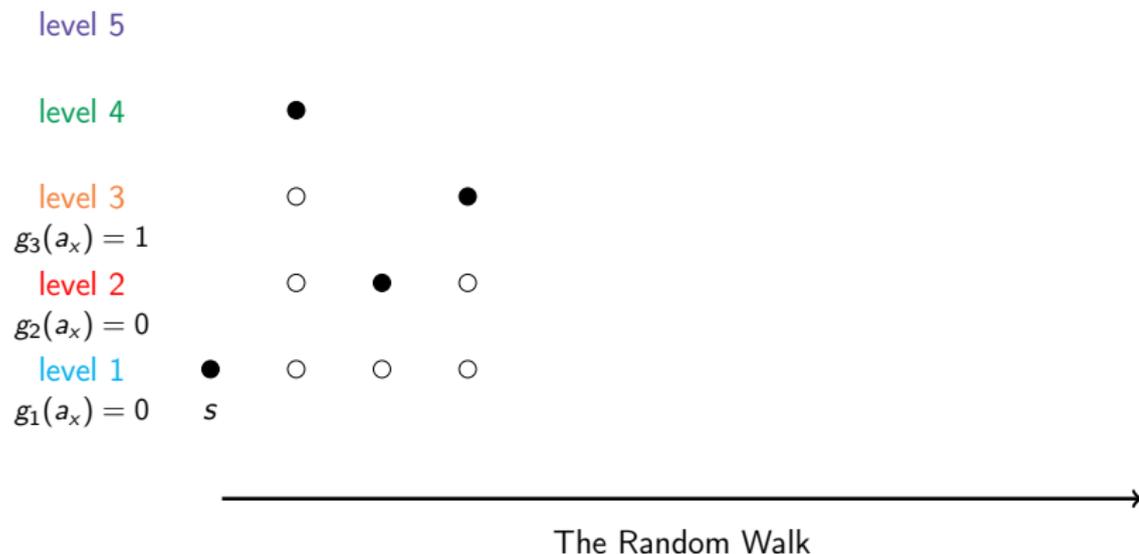
Our Construction via Iterative Restriction



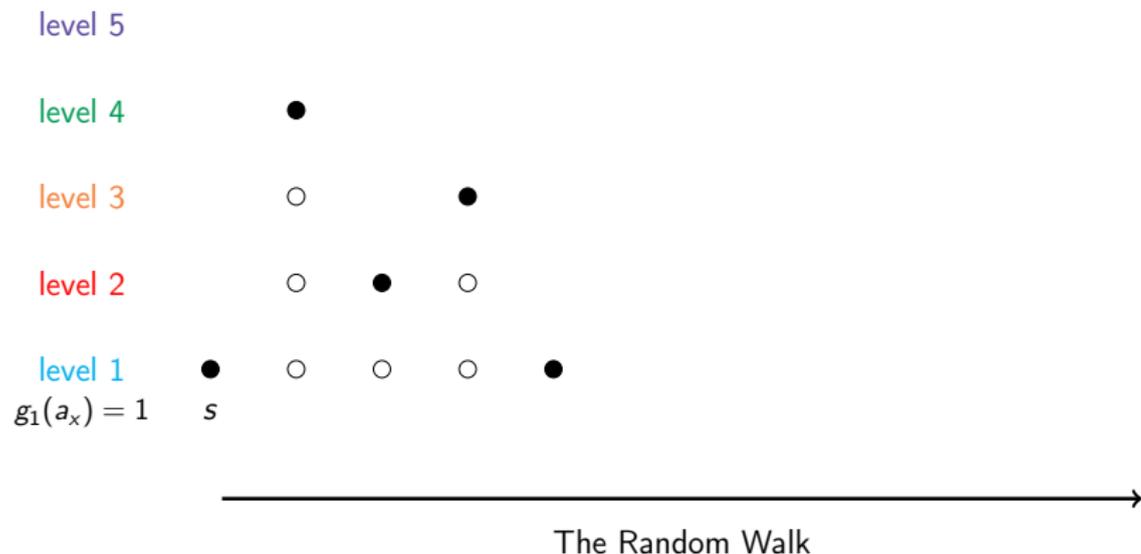
Our Construction via Iterative Restriction



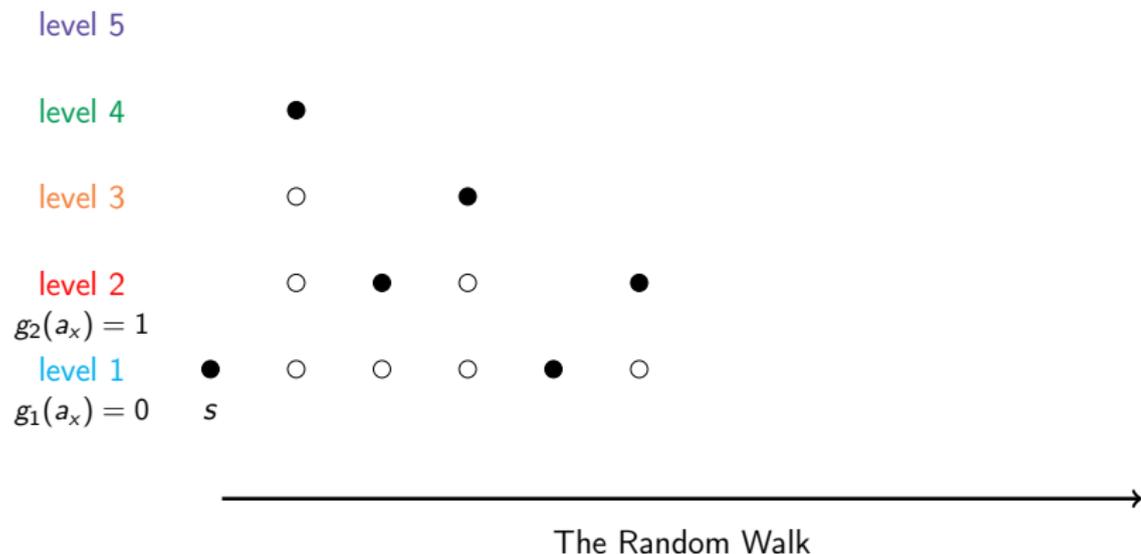
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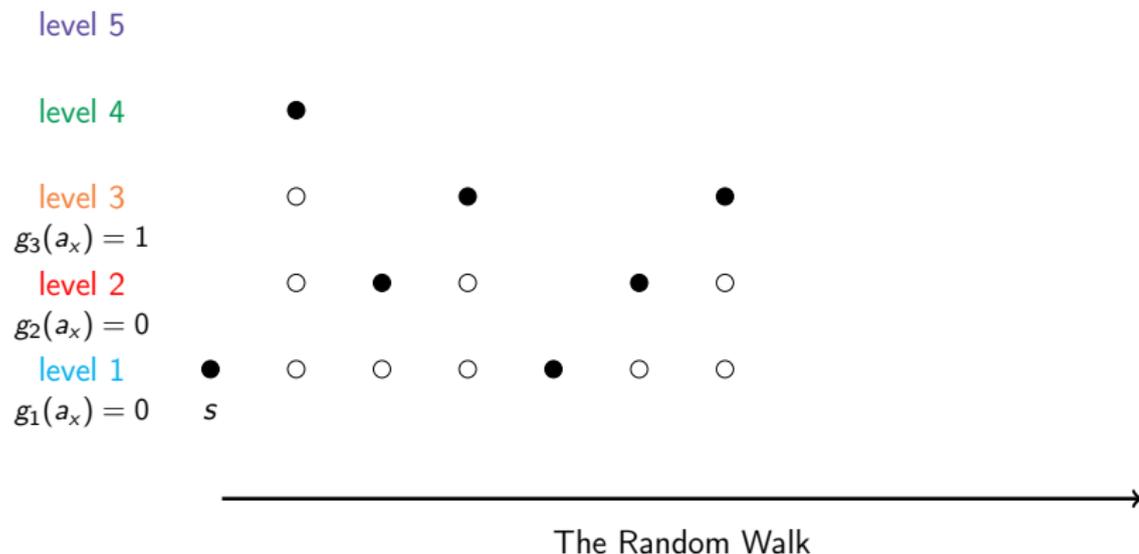
Our Construction via Iterative Restriction



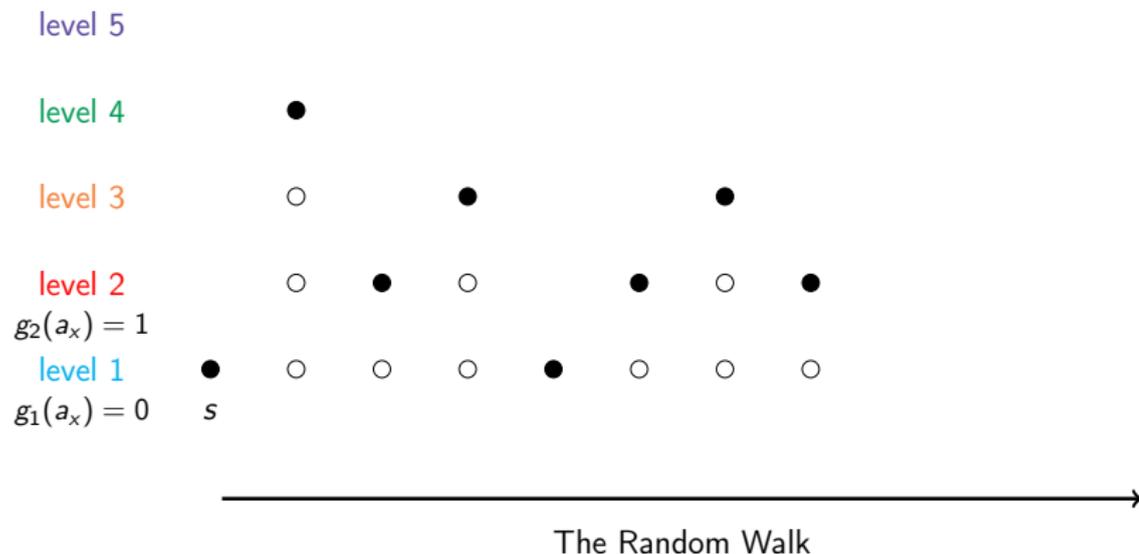
Our Construction via Iterative Restriction



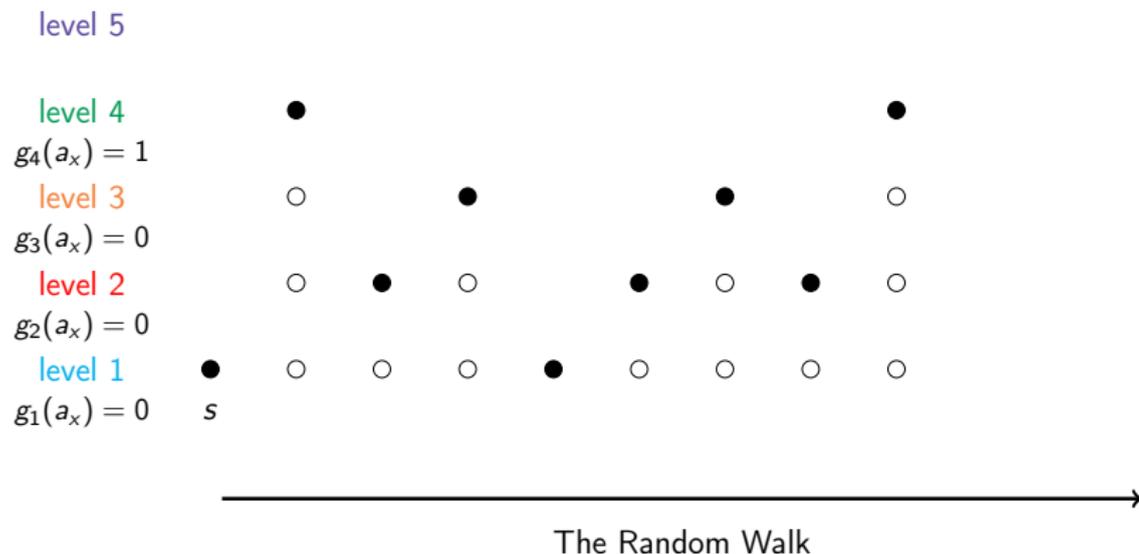
Our Construction via Iterative Restriction



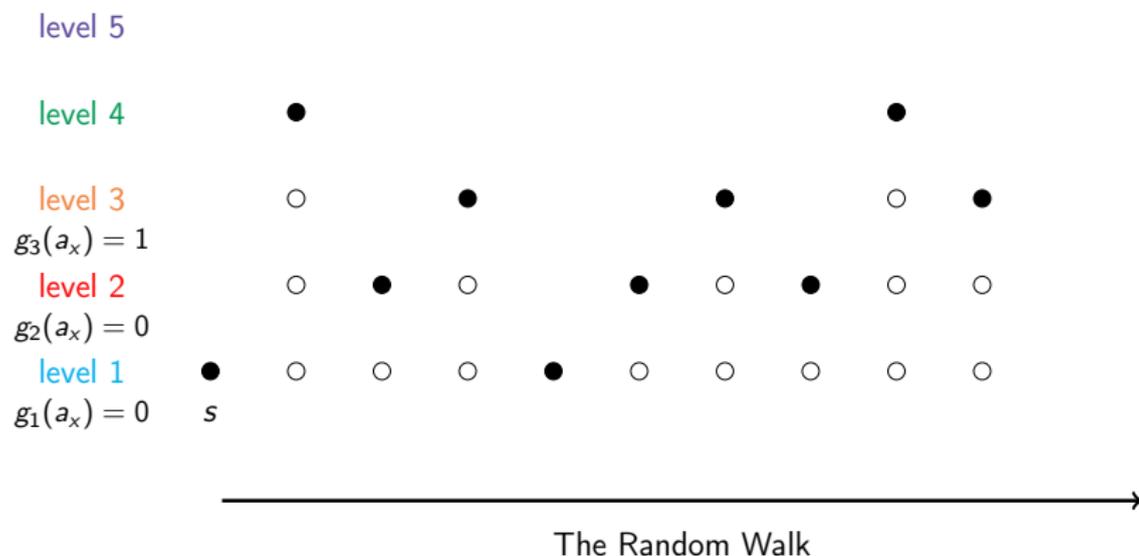
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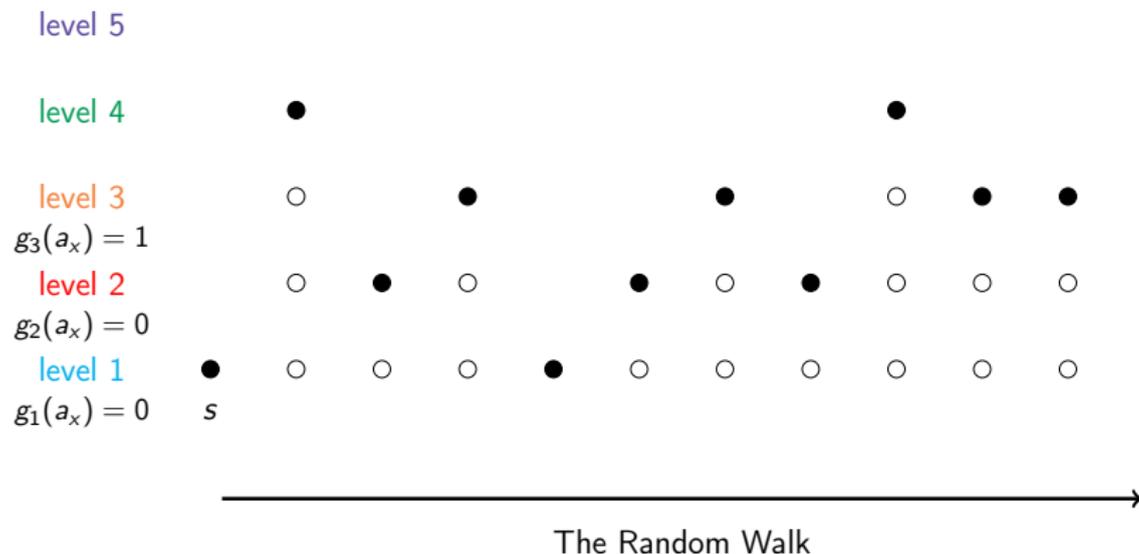
Our Construction via Iterative Restriction



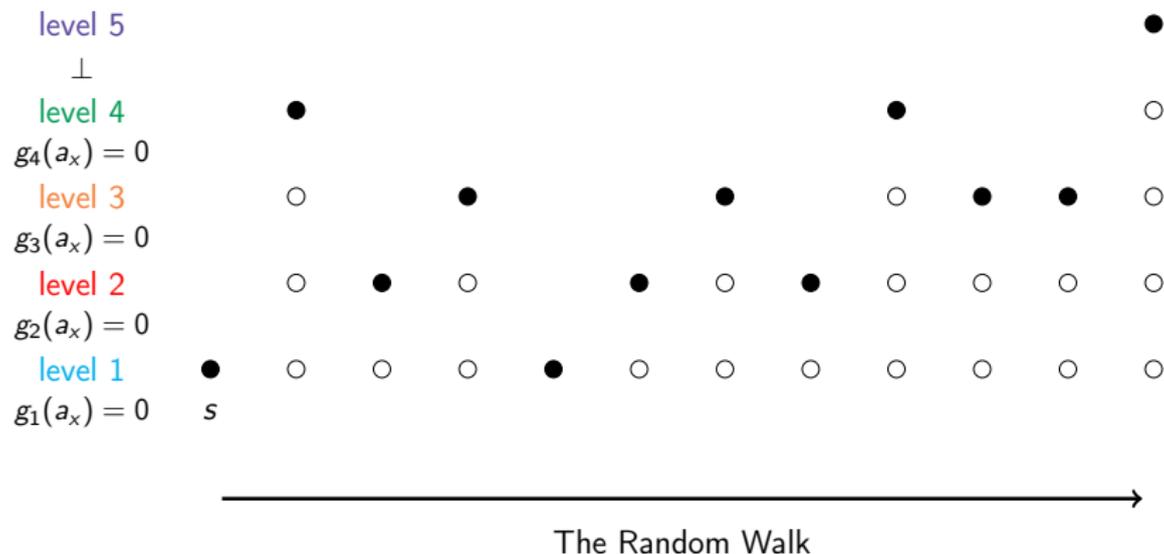
Our Construction via Iterative Restriction



Our Construction via Iterative Restriction

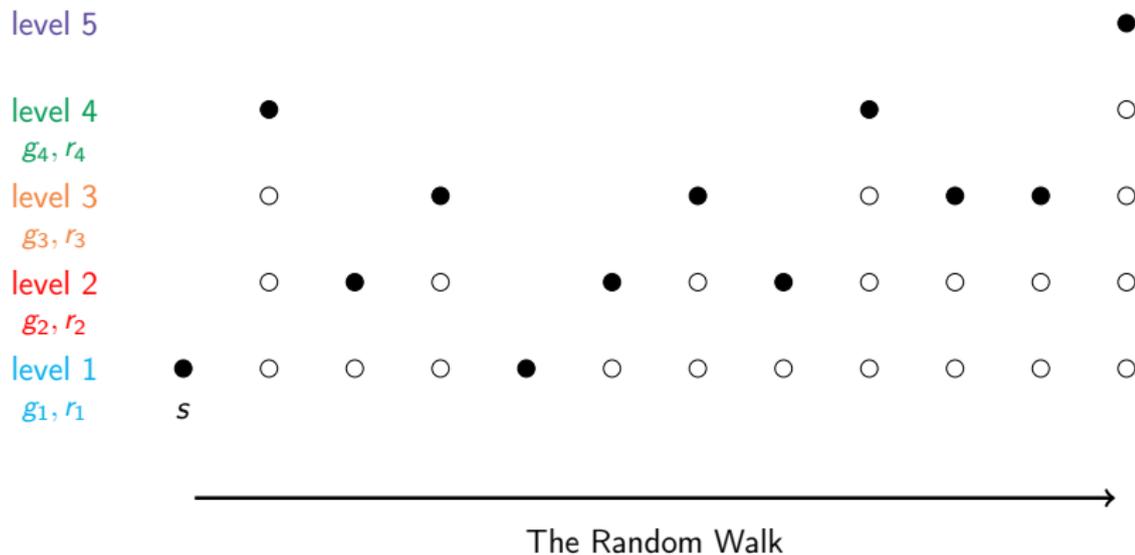


Our Construction via Iterative Restriction

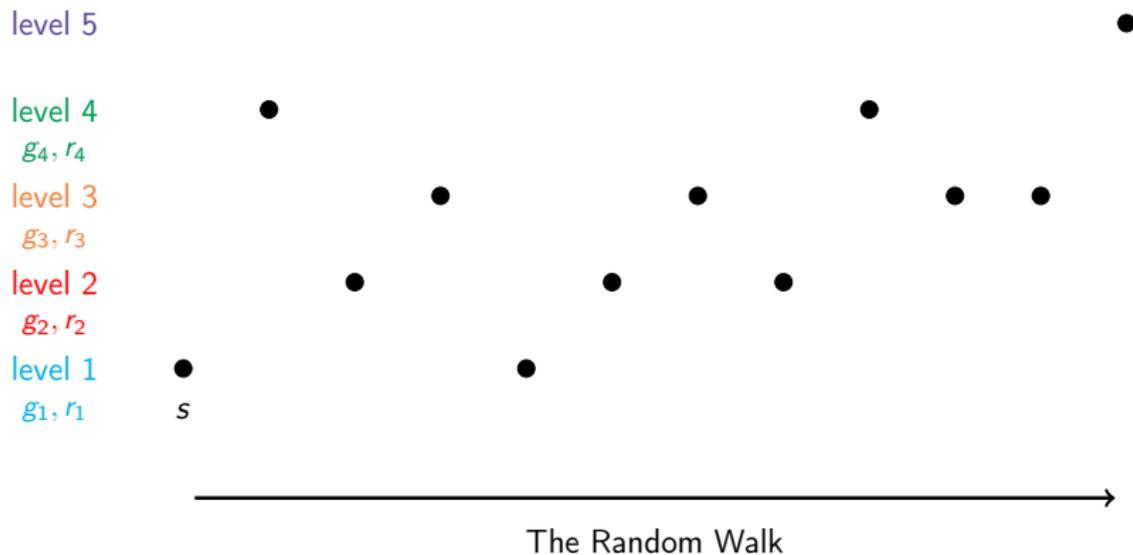


Key Ideas in Our Analysis

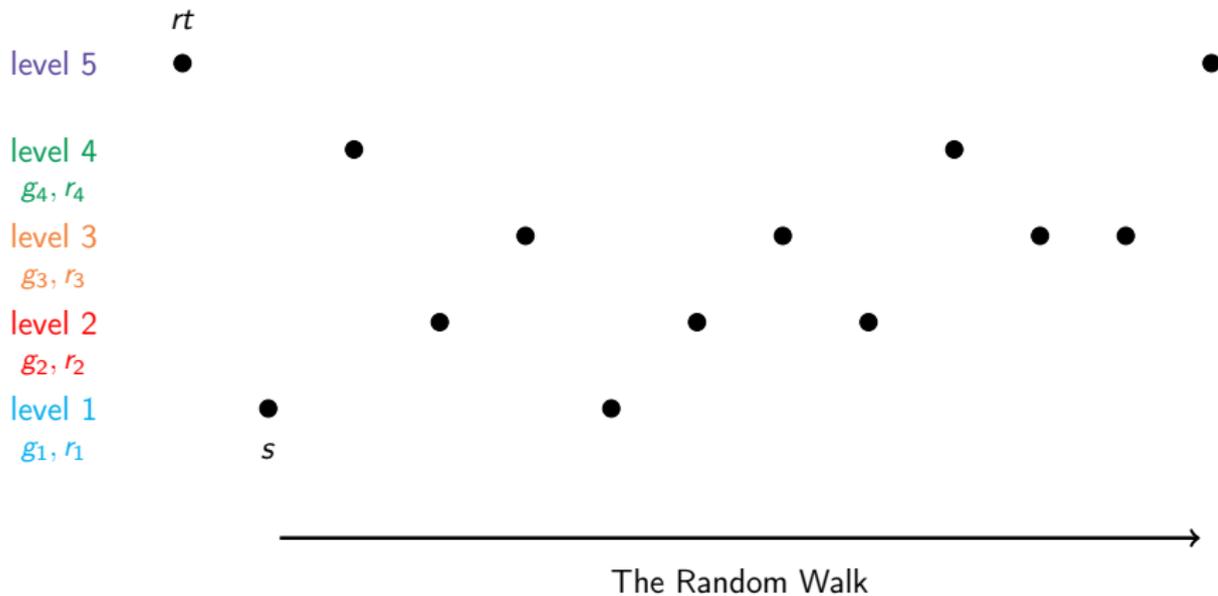
Dependency Tree



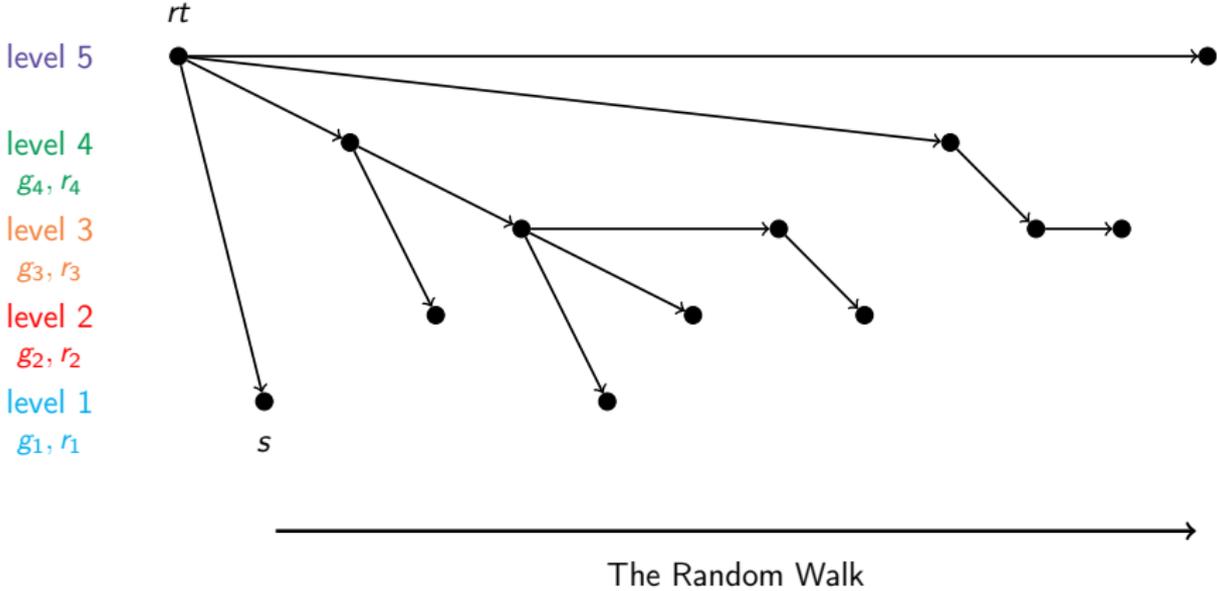
Dependency Tree



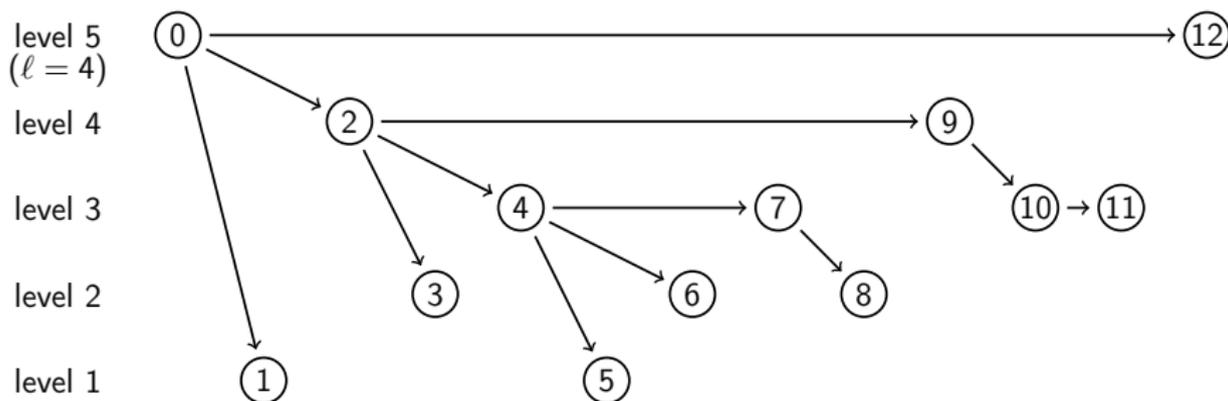
Dependency Tree



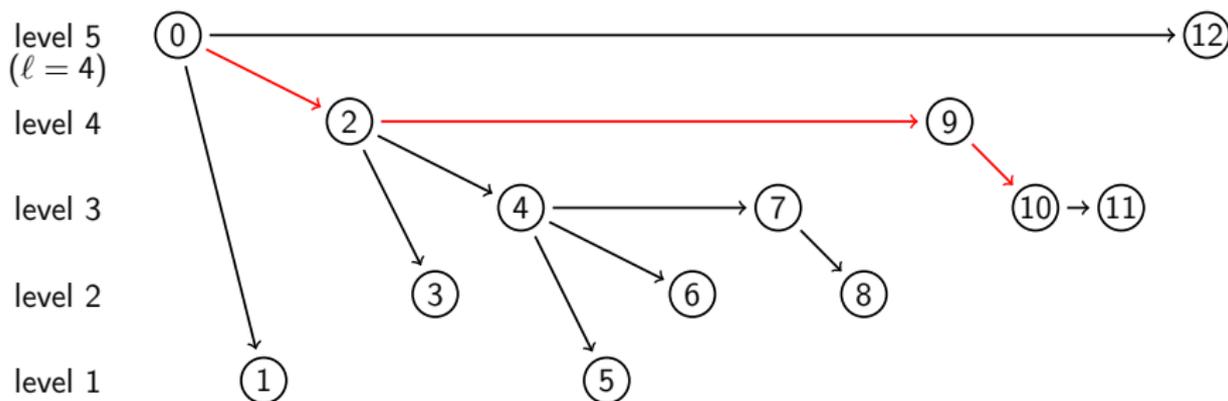
Dependency Tree



Dependency Tree

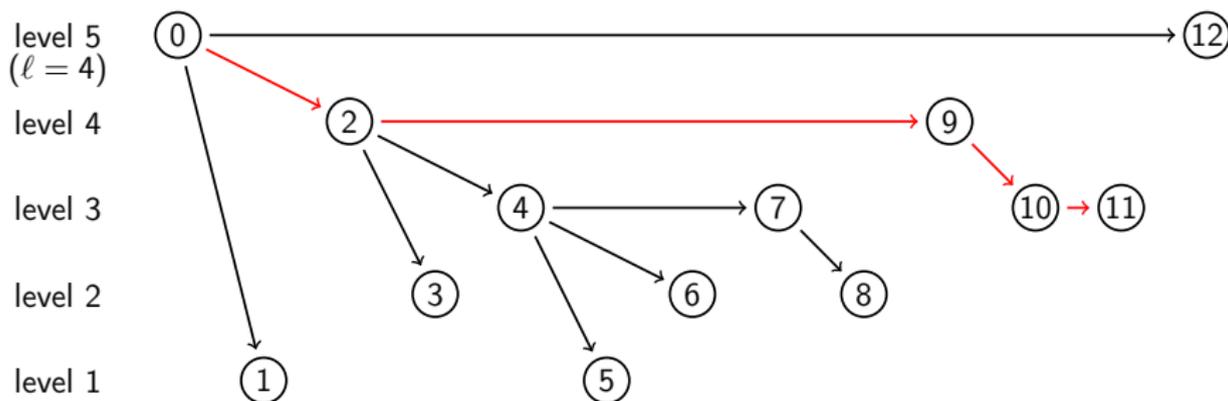


Dependency Tree



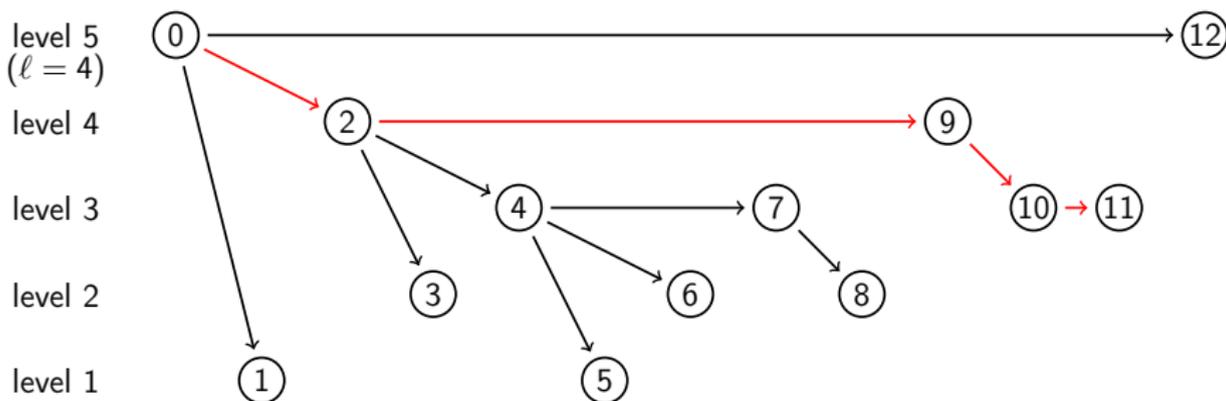
- We index a node by the shape of its path, e.g. $\vec{k}_{10} = (0, 0, 1, 2)$.

Dependency Tree



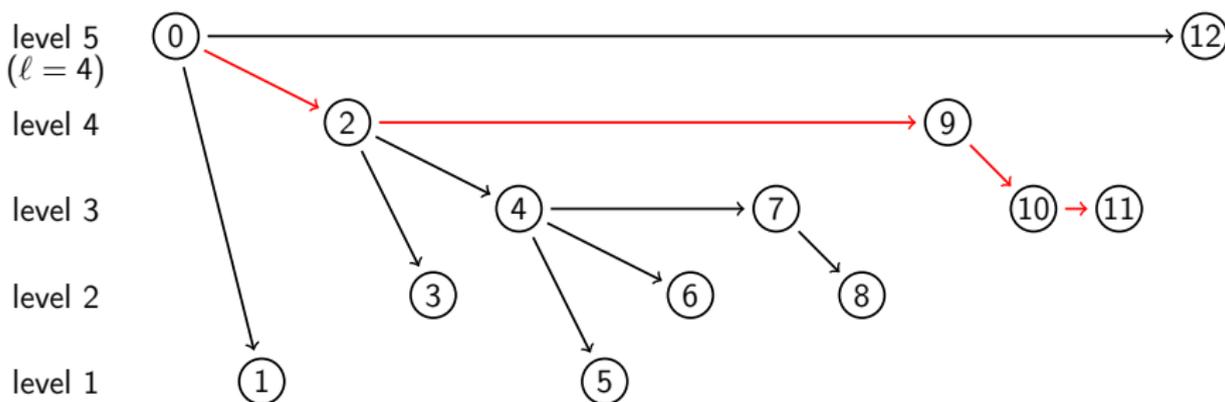
- We index a node by the shape of its path, e.g. $\vec{k}_{11} = (0, 0, 2, 2)$.

Dependency Tree



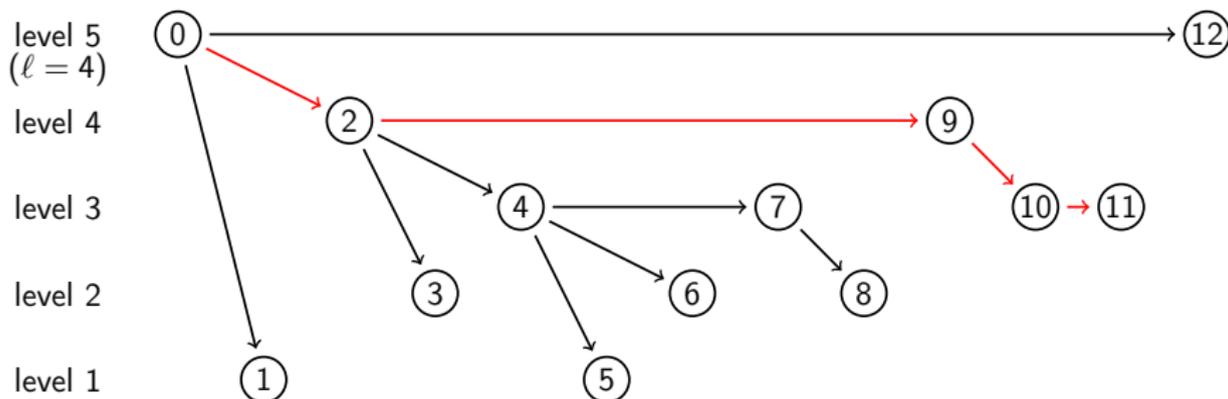
- We index a node by the shape of its path, e.g. $\vec{k}_{11} = (0, 0, 2, 2)$.
- Consider \vec{k}_x . Fix x , \vec{k} is a random variable. Fix \vec{k} , x is a random variable.

Dependency Tree



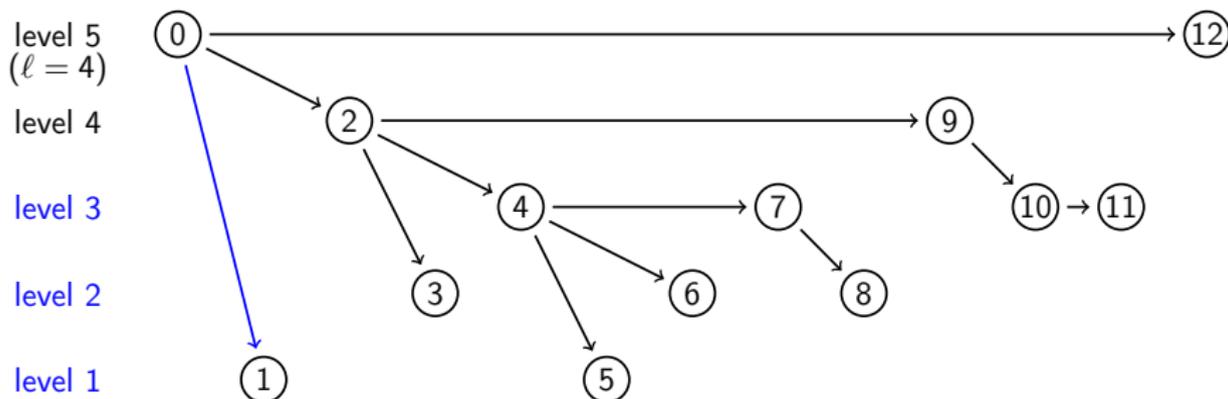
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- Consider \vec{k}_x . Fix x , \vec{k} is a random variable. Fix \vec{k} , x is a random variable.
- We fix index \vec{k} and let x be the random variable (which may not exist).

Memory Eraser on Dependency Tree



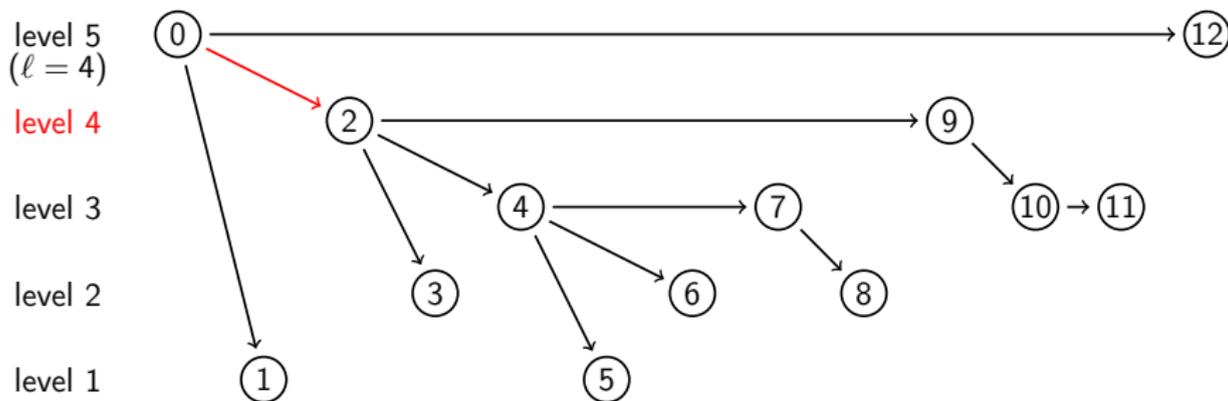
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Memory Eraser on Dependency Tree



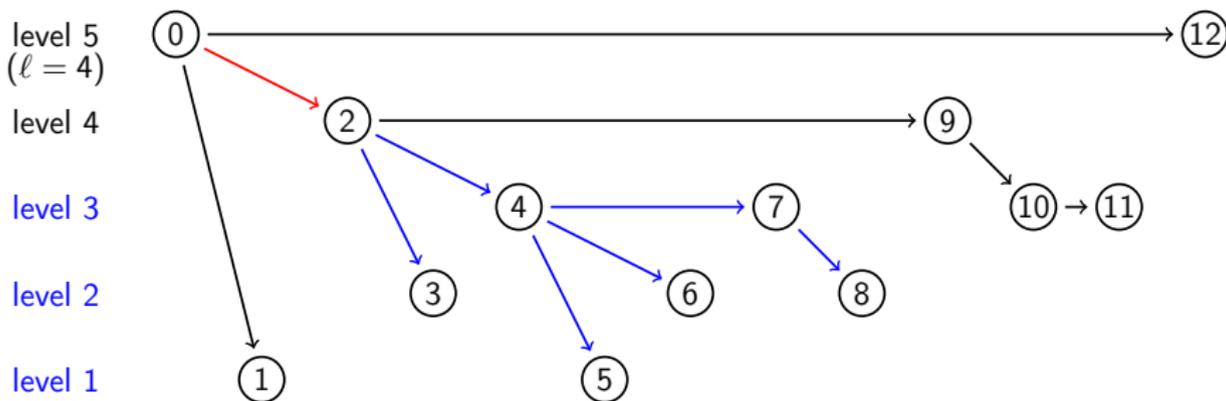
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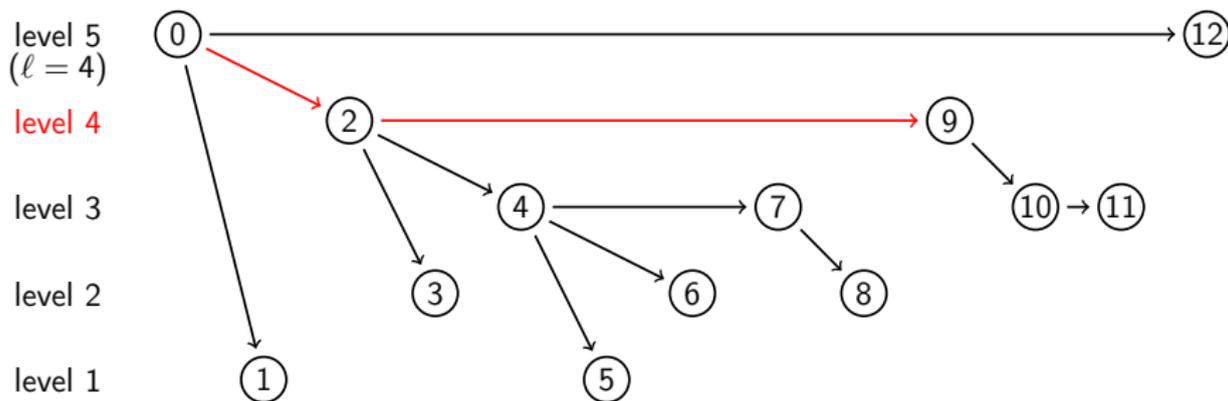
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Memory Eraser on Dependency Tree



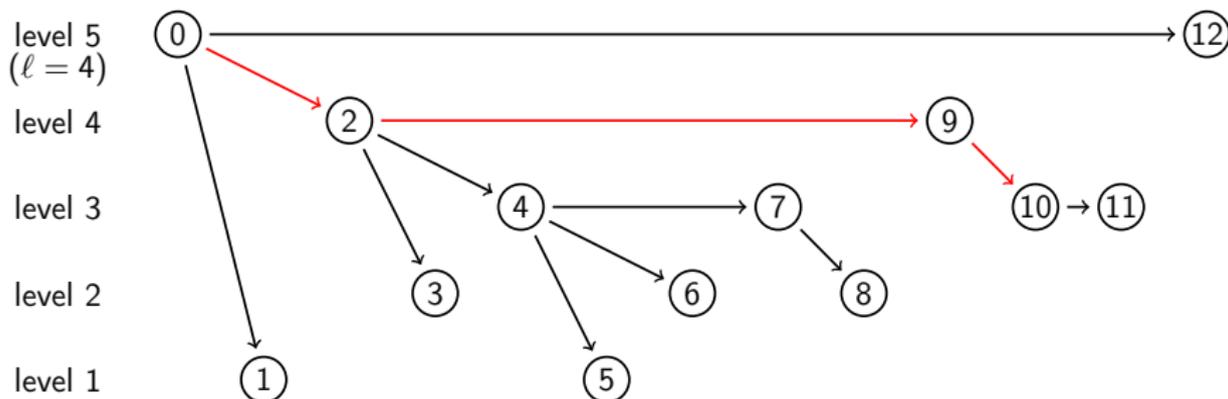
- Fix $\vec{k} = (0, 0, 2, 2)$.
- Blue part is a random variable. But it will finally end up with a node with level ≥ 4 .

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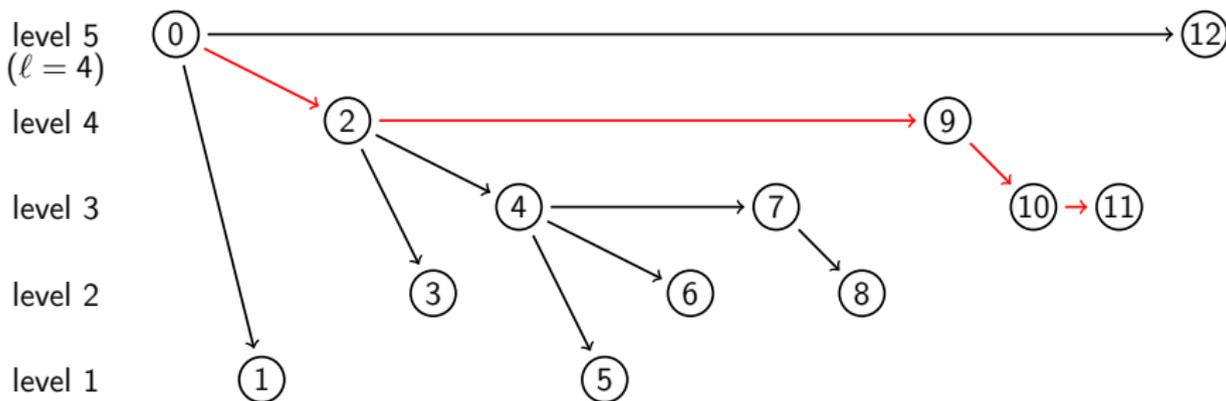
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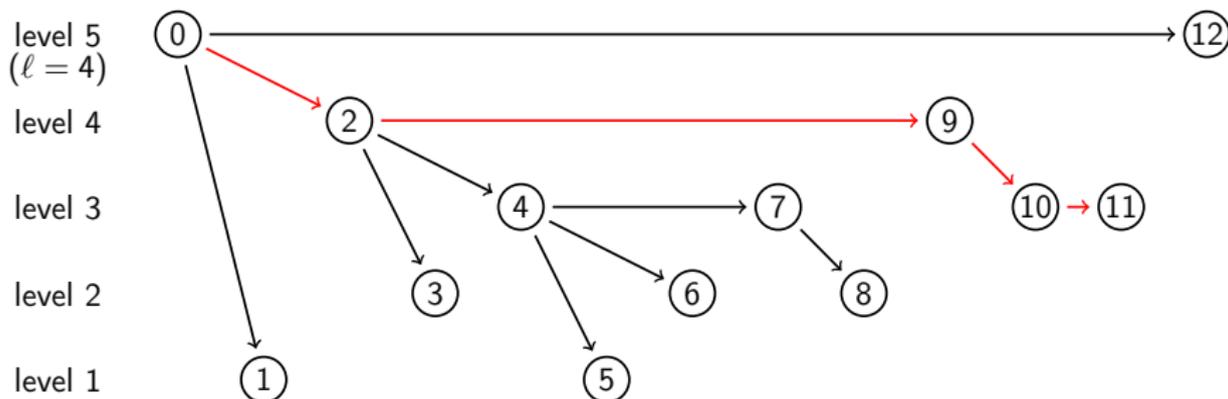
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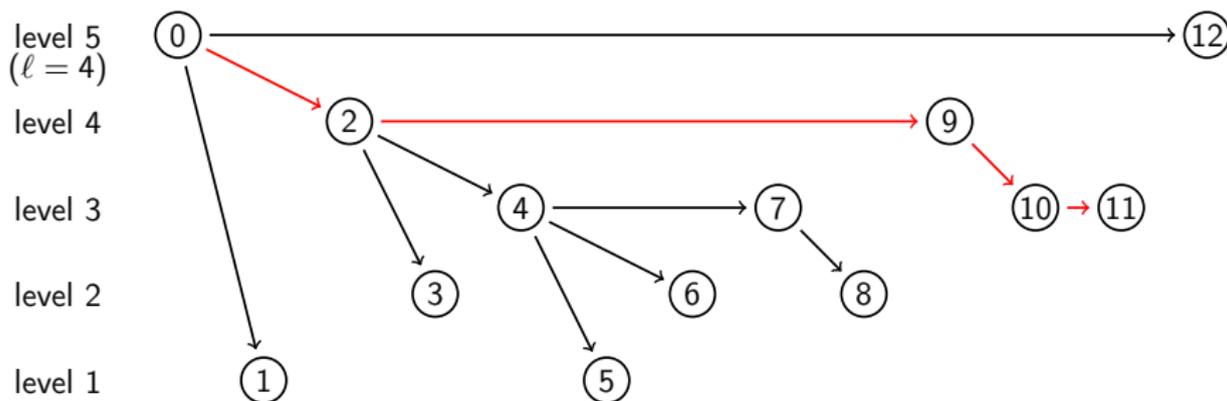
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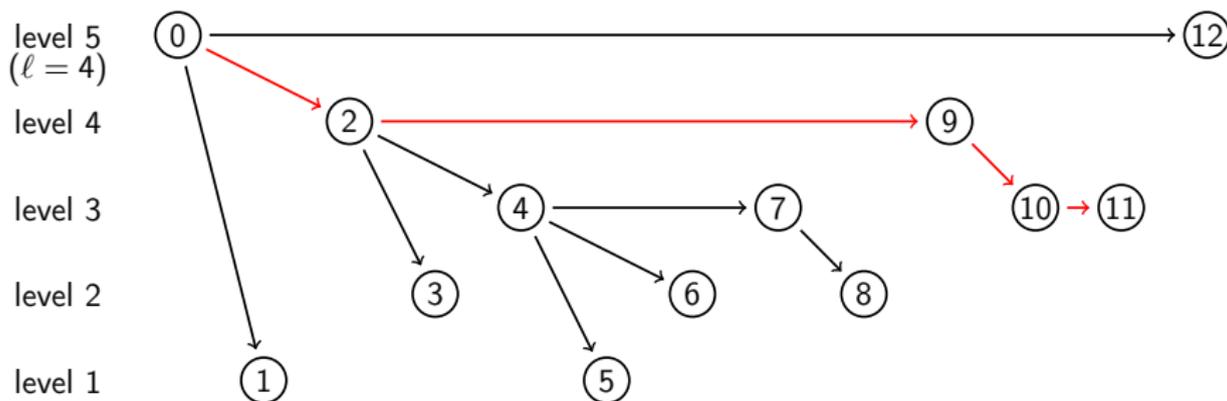
- Fix $\vec{k} = (0, 0, 2, 2)$.
- Blue part is a random variable. But it will finally end up with a node with level ≥ 4 .
- One issue: What if $a_{w_2} = a_{w_9}$?

(Locally Simulatable) Extended Walk



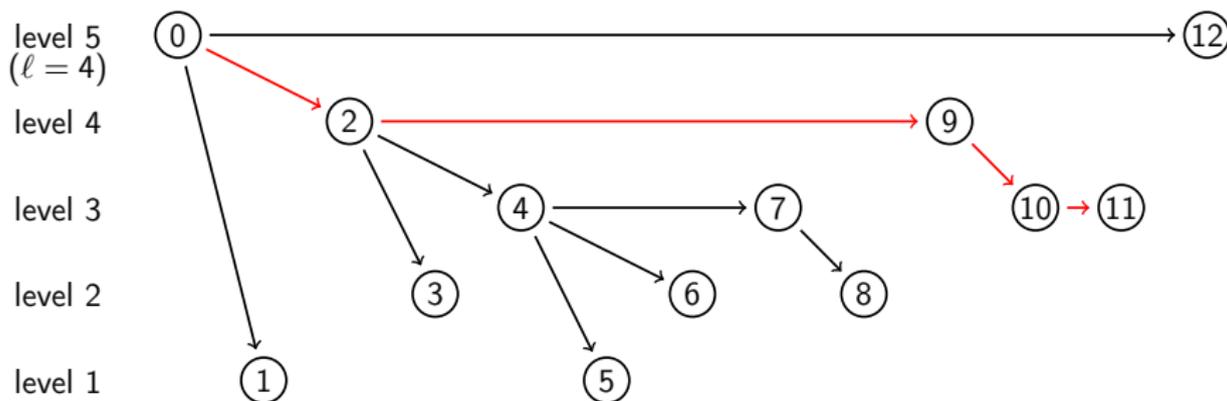
- Instead of original walk w , we look at extended walk w^* .

(Locally Simulatable) Extended Walk



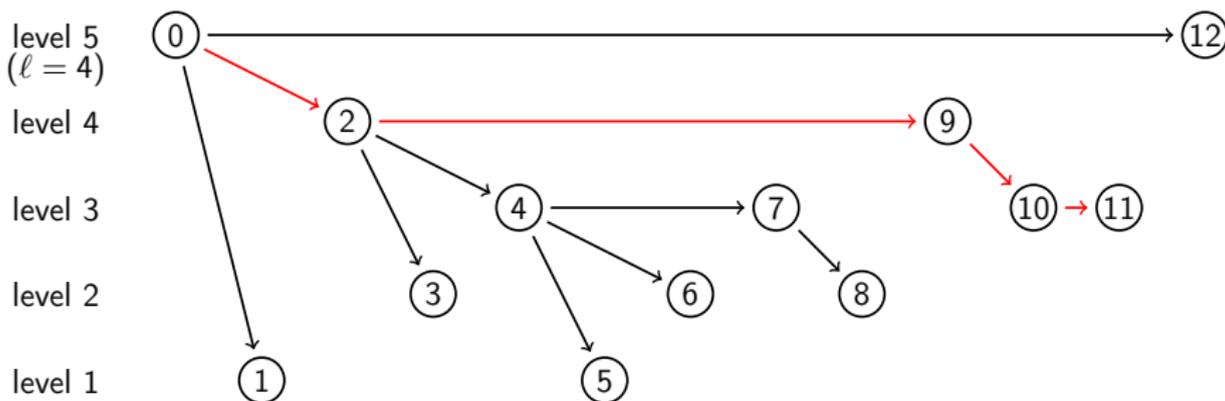
- Instead of original walk w , we look at extended walk w^* .
- Once a position in our memory is queried twice, we replace it with true randomness.

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- w^* is *locally simulatable* in the sense that each query position can be uniquely determined by memory.

(Locally Simulatable) Extended Walk



- Instead of original walk w , we look at extended walk w^* .
- Once a position in our memory is queried twice, we replace it with true randomness.
- w^* is *locally simulatable* in the sense that each query position can be uniquely determined by memory.
- w and w^* agree if w^* has no collision $a_{w_i^*} = a_{w_j^*}$.

Good = All - Bad

Recall our goal.

Our Main Lemma

- $\mathbb{E}[|f^*(s)|] \leq O(\sqrt{n})$
- $\Pr[u \in f^*(s)] \geq \Omega(1/\sqrt{n}), \forall u \in [n]$
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- All: $E[\#\{t | w_t^* = u\}]$

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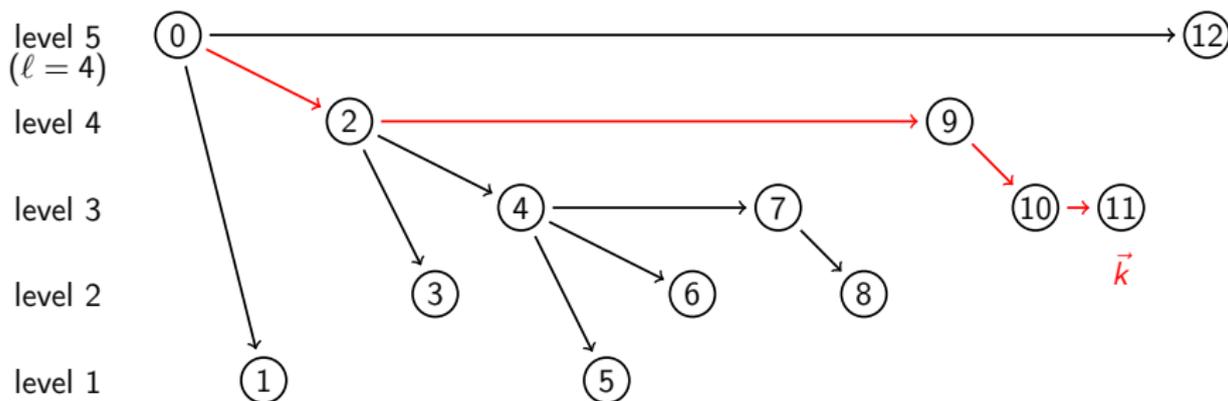
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- All: $E[\#\{t | w_t^* = u\}]$
- Bad:

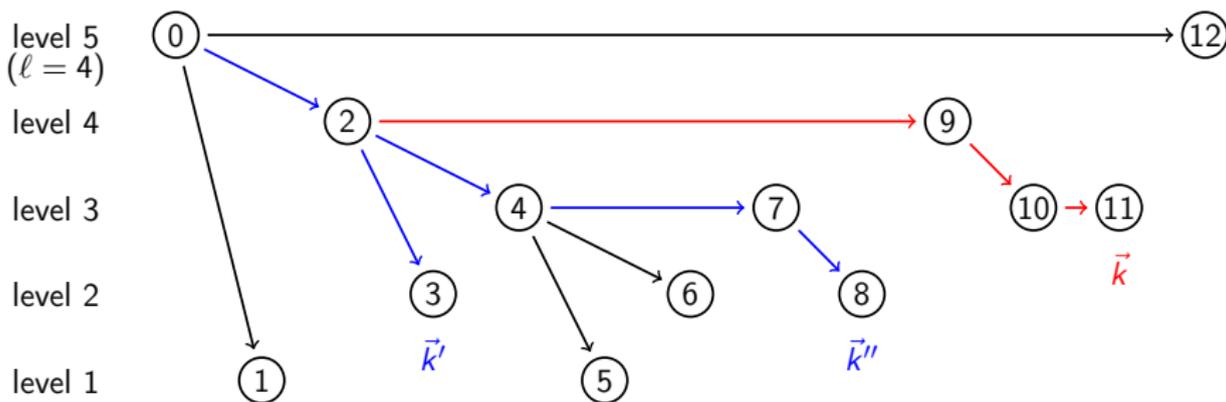
$$\begin{aligned} & E[\#\{t | w_t^* = u, \exists t' \neq t'', a_{w_{t'}^*} = a_{w_{t''}^*}\}] \\ & \leq E[\#\{t, t' \neq t'' | w_t^* = u, a_{w_{t'}^*} = a_{w_{t''}^*}\}] \end{aligned}$$

Good = All - Bad



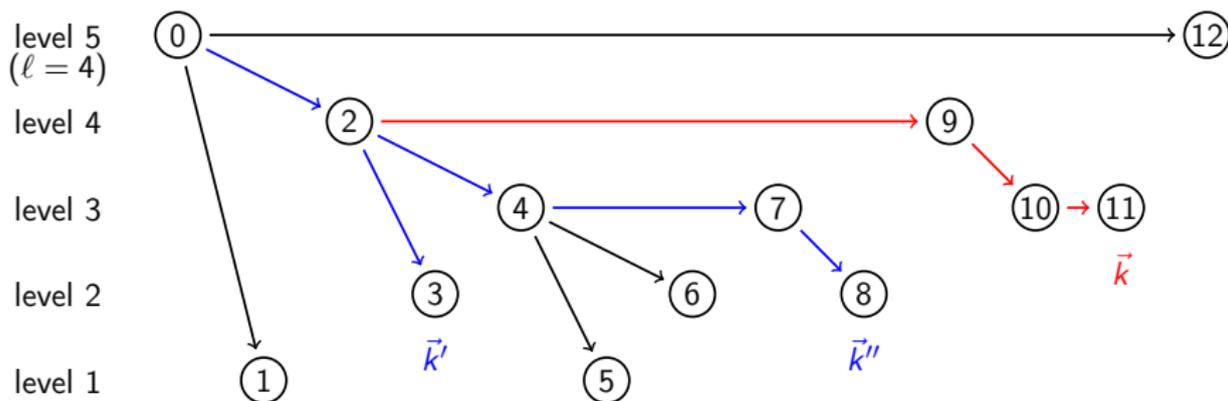
$$E[\#\{t | w_t^* = u\}] = \sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n}$$

Good = All - Bad



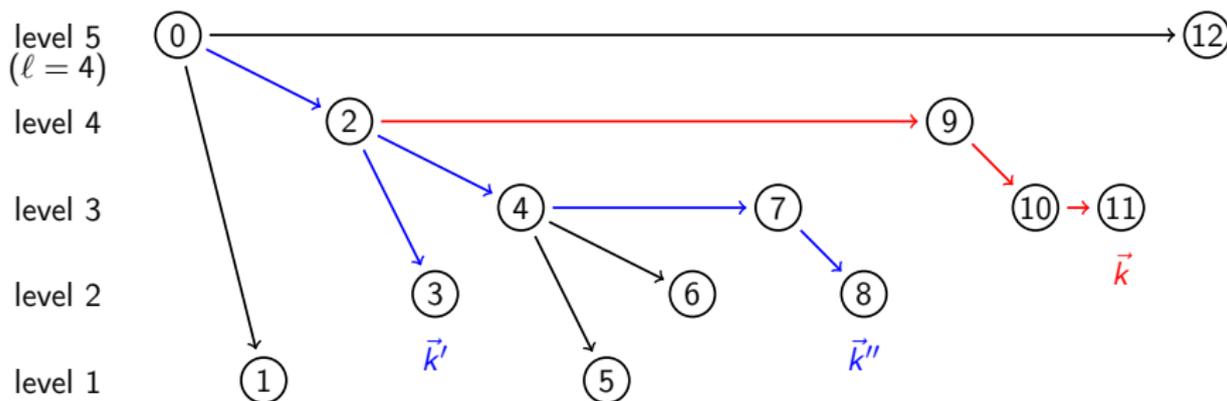
$$E[\#\{t, t' \neq t'' | w_t^* = u, a_{w_{t'}}^* = a_{w_{t''}}^*\}] = \sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2}$$

Good = All - Bad



$$\text{Good} = \sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n} - \sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2}$$

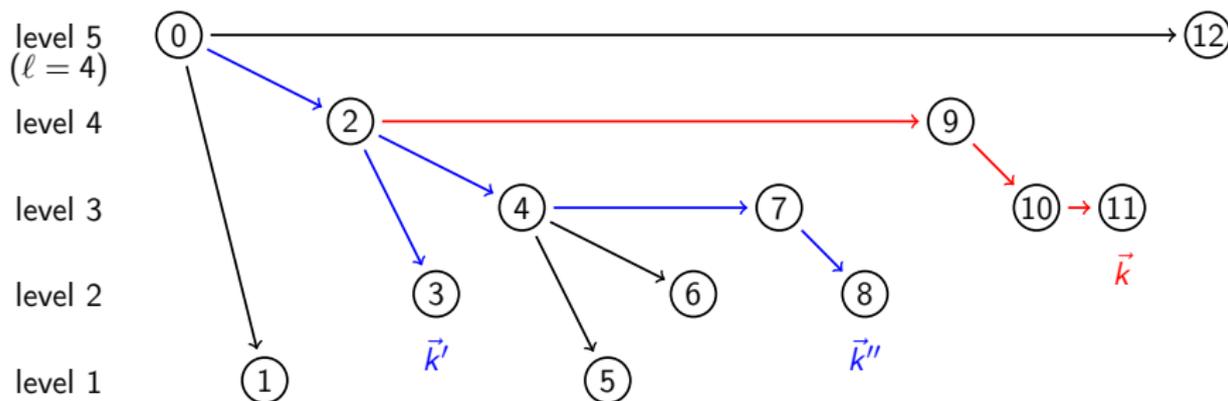
Good = All - Bad



$$\text{Good} = \sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n} - \sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2}$$

$$\sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n} = \frac{1}{n} \prod_{i=1}^{\ell} \sum_{k_i=0}^{\infty} 2^{-k_i} = \frac{2^\ell}{n}$$

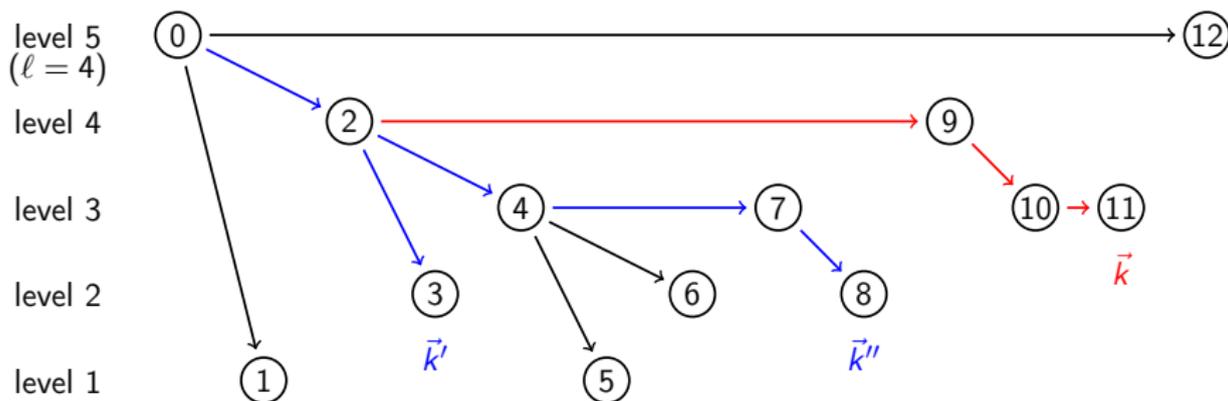
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$$\text{Good} = \sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n} - \sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2}$$

$$\sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2} = \frac{8^\ell}{n^2}$$

Good = All - Bad



$$\text{Good} = \sum_{\vec{k}} \frac{2^{-(k_1+k_2+\dots+k_\ell)}}{n} - \sum_{\vec{k}, \vec{k}', \vec{k}''} \frac{2^{-\|\vec{k}\|_1 - \|\vec{k}'\|_1 - \|\vec{k}''\|_1}}{n^2} = \frac{2^\ell}{n} - \frac{8^\ell}{n^2}$$

$$\text{Let } \ell \leftarrow \frac{1}{2} \log n - 100. \quad \frac{2^\ell}{n} - \frac{8^\ell}{n^2} = \frac{2^{-100}}{\sqrt{n}} - \frac{2^{-300}}{\sqrt{n}} = \Omega\left(\frac{1}{\sqrt{n}}\right).$$

Our Main Lemma

- $\mathbb{E}[|f^*(s)|] \leq O(\sqrt{n})$
- $\Pr[u \in f^*(s)] \geq \Omega(1/\sqrt{n}), \forall u \in [n]$
- Even for this simple case, there is so much more technical challenges that is hidden in this talk.

Open Problems

- **Time-space Tradeoffs**

In this work, we only solved the case when $S = \tilde{O}(1)$. Can we extend it to the full tradeoff?

- **Shorter Seed Length**

In this work, our seed length is $O(\log^3 n \log \log n)$. Can this be improved?

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